



unsloth

Deep-Dive: RL, Kernels, Agents & Quantization

www.unsloth.ai

Daniel Han

Co-founder



Access the slides





Andrej Karpathy @karpathy · Mar 7

Beautiful work / attention to detail trying to get Gemma to train. There are so many foot guns here to be super careful with. If you don't throw any errors, they silently make your network worse.

A great example of what I wrote about in my "A Recipe for Training LLMs" [Show more](#)

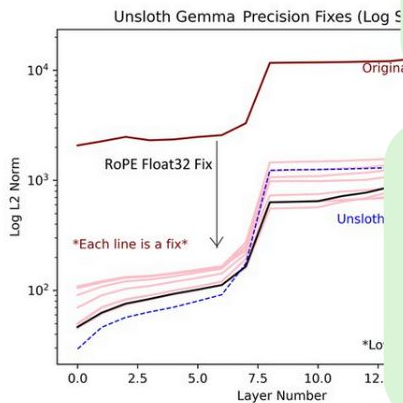
Daniel Han @danielhanchen · Mar 7

Found more bugs for #Gemma:

1. Must add <bos>
2. There's a typo for <end_of_turn>model
3. $\sqrt{3072}=55.4256$ but `bfloat16` is 55.5
4. Layernorm (w+1) must be in float32...

[Show more](#)

[Show this thread](#)



Gradient Accumulation Bug Fix

Async Offloaded Gradient Checkpointing

We work with HF, Google, Meta, Mistral to fix Gemma, Llama, Mistral, Phi bugs

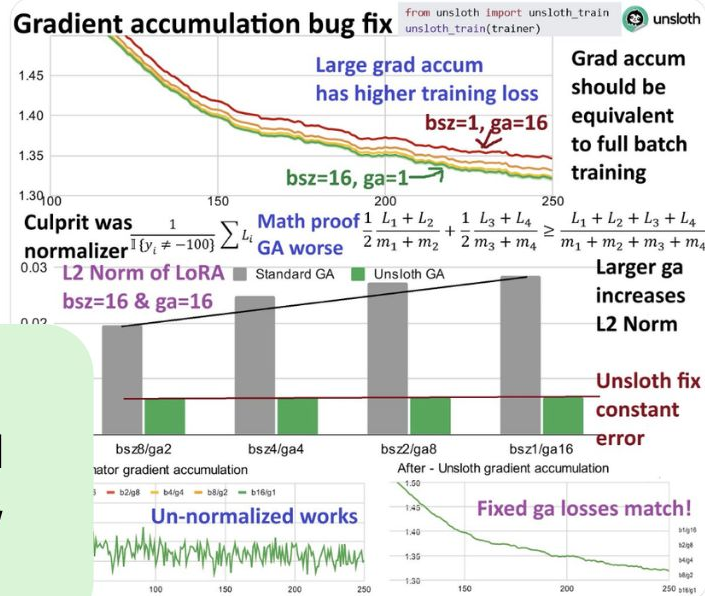


Daniel Han @danielhanchen · Oct 15

Fixed a bug which caused all training losses to diverge for large gradient accumulation sizes.

1. First reported by @bnjmn_marie, GA is supposed to be mathematically equivalent to full batch training, but losses did not match.
2. We reproed the issue, and further investigation

[Show more](#)



55

335

2.6K

469K

21

173

755

303K

unsloth

[Phi-4 Bug Fixes by Unsloth](#) (via) This explains why I was seeing weird `<|im_end|>` suffixes during my [experiments with Phi-4](#) the other day: it turns out the Phi-4 tokenizer definition as released by Microsoft had a bug in it, and there was a small bug in the chat template as well.

Daniel and Michael Han figured this out and have now published [GGUF files with their fixes](#) on Hugging Face.

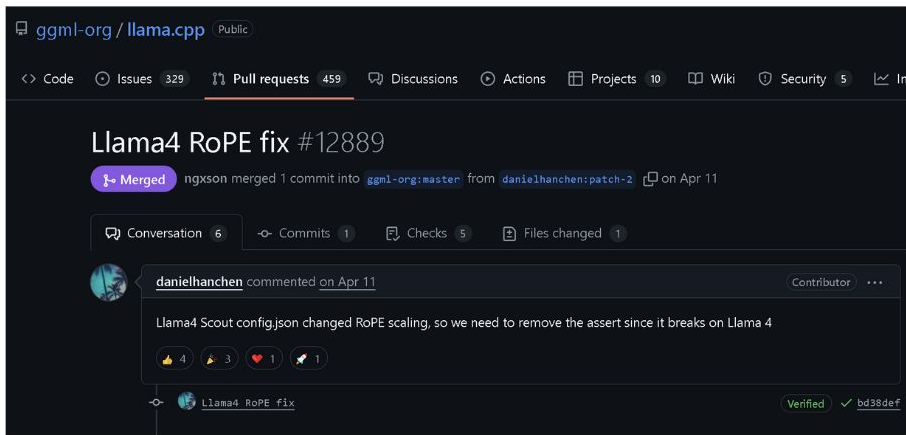
Posted [11th January 2025](#) at 1:20 am

Open-source contributions

Phi-3 + 4 Bug fixes
Merged by Microsoft

Multiple Llama 4 fixes
and contributions to
llama.cpp

Recently worked with
Qwen team on Qwen3
and Mistral on Devstral





10 million+

monthly downloads

10M+

monthly downloads
on 🤗 Hugging Face

40K

stars on GitHub



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main

11 Branches

13 Tags

Go to file

Add file

<> Code

 danielhanchen

Update rl.py

3340eaa · 7 hours ago

🕒 1,324 Commits

📁 .github	Update issue templates	3 days ago
📁 images	Uploading HQ Unsloth Sticker	last month
📁 tests	reroute merge logic language models + comprehensive tests...	11 hours ago
📁 unsloth	Update rl.py	7 hours ago
📄 .gitignore	MoE Kernel (#2465)	last month
📄 CODE_OF_CONDUCT.md	Added missing code of conduct (#2416)	last month
📄 CONTRIBUTING.md	Added missing code of conduct (#2416)	last month
📄 LICENSE	Auto Healing Tokenizer (#283)	last year
📄 README.md	Update README.md	last week
📄 pyproject.toml	Bug fixes (#2651)	5 days ago
📄 unsloth-cli.py	Bug fixes (#1516)	5 months ago

About

Finetune Qwen3, Llama 4, TTS, DeepSeek-R1 & Gemma 3 LLMs 2x faster with 70% less memory! 🐈

[unsloth.ai](#)

- text-to-speech
- tts
- llama
- lora
- gemma
- mistral
- fine-tuning
- finetuning
- llm
- llms
- qlora
- qwen
- deepseek
- unsloth
- llama3
- deepseek-r1
- gemma3
- qwen3
- llama4
- llama-4

- 📖 Readme
- 📄 Apache-2.0 license
- 📄 Code of conduct
- 📄 Activity
- 📄 Custom properties
- ☆ 39.9k stars
- 👁 234 watching
- 🔗 3.2k forks



Unsloth AI **Enterprise** Company ✓ Verified

<https://unsloth.ai> [X unslothai](#) [unslothai](#)



Hugging Face

Activity Feed

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AI & ML interests

Hey! We're focusing on making AI more accessible to everyone!

Dynamic 2.0 quants

DeepSeek R1-0528

Expect Bug fixes + updates constantly for chat templates, tokenizers etc.

GGUF, 4-bit, original

Collections 21

^ Collapse

DeepSeek R1 (All Versions) >

DeepSeek-R1-0528 is here! The most powerful reasoning open L...

 unsloth/DeepSeek-R1-0528-GGUF

 Text Generation • Updated about 9 h... • ↓ 51.2k • ♥ 124

 unsloth/DeepSeek-R1-0528-Qwen3-8B-GGUF

 Text Generation • Updated 2 days ago • ↓ 116k • ♥ 116

 unsloth/DeepSeek-R1-0528-Qwen3-8B-unsloth...

 Text Generation • Updated 5 days ago • ↓ 1.78k • ♥ 2

 unsloth/DeepSeek-R1-0528

Unsloth Dynamic 2.0 Quants >

New 2.0 version of our Dynamic GGUF + Quants. Dynamic 2.0 ac...

 unsloth/DeepSeek-R1-0528-GGUF

 Text Generation • Updated about 9 h... • ↓ 51.2k • ♥ 124

 unsloth/DeepSeek-R1-0528-Qwen3-8B-GGUF

 Text Generation • Updated 2 days ago • ↓ 116k • ♥ 116

 unsloth/Devstral-Small-2505-GGUF

 Text2Text Generation • Updated 9 days ... • ↓ 113k • ♥ 80

 unsloth/Phi-4-reasoning-plus-GGUF

Qwen3 >

Qwen's new Qwen3 models. In Unsloth Dynamic 2.0, GGUF, 4-bi...

 unsloth/Qwen3-30B-A3B-GGUF

 Text Generation • Updated 4 days ago • ↓ 168k • ♥ 193

 unsloth/Qwen3-32B-GGUF

 Text Generation • Updated 10 days ago • ↓ 69k • ♥ 63

 unsloth/Qwen3-235B-A22B-GGUF

 Text Generation • Updated 10 days ago • ↓ 45k • ♥ 53

Llama 4 >

Meta's new Llama 4 multimodal models, Scout & Maverick. Incl...

 unsloth/Llama-4-Scout-17B-16E-Instruct-G...

 Image-Text-to-Text • Updated 5 days ago • ↓ 108k • ♥ 87

 unsloth/Llama-4-Maverick-17B-128E-Instru...

 Image-Text-to-Text • Updated 6 days ago • ↓ 43.1k • ♥ 23

 unsloth/Llama-4-Scout-17B-16E-Instruct

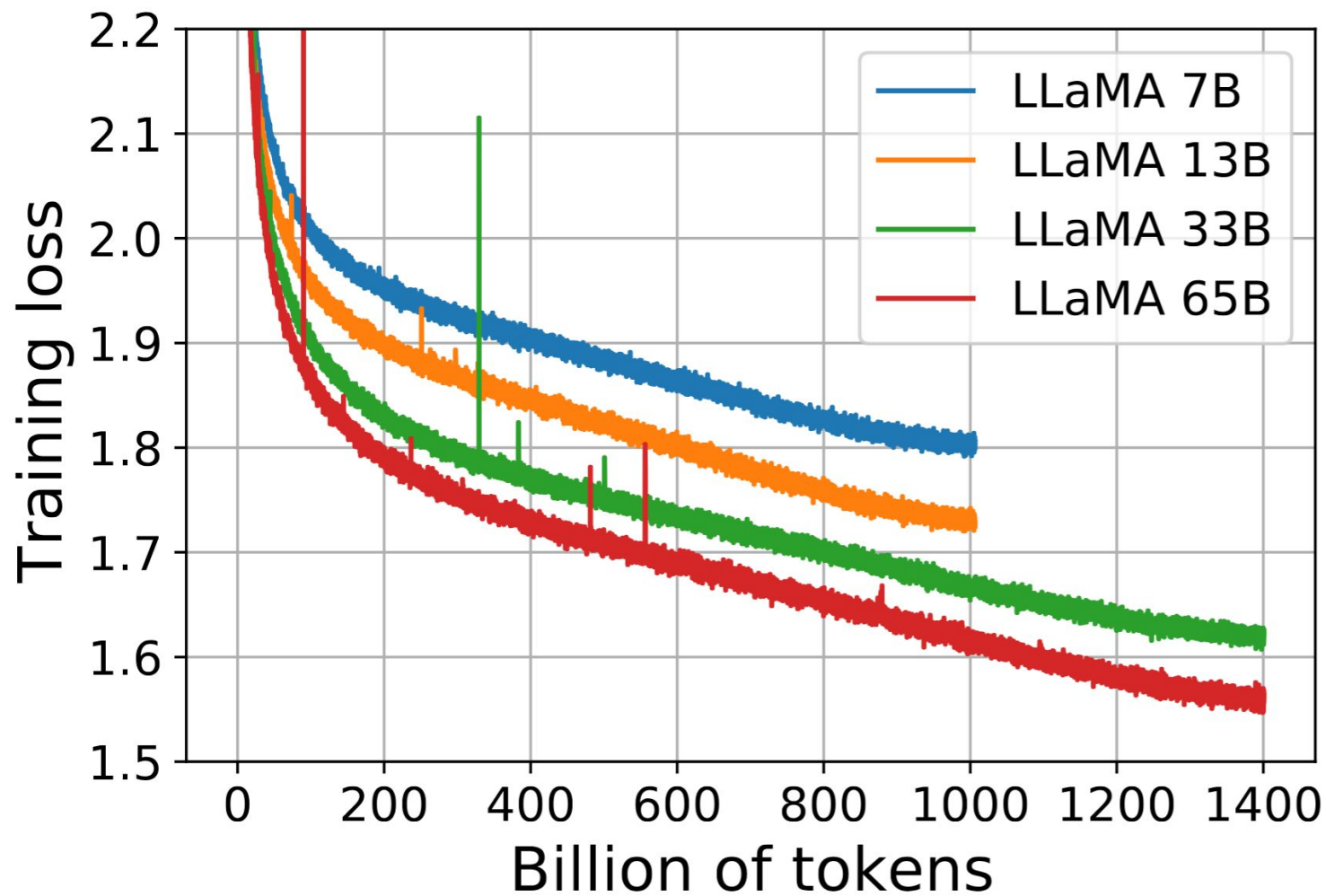
 Image-Text-to-Text • Updated 7 days ago • ↓ 2.99k • ♥ 55

LLaMA: Open and Efficient Foundation Language Models

**Hugo Touvron*, Thibaut Lavril*, Gautier Izacard*, Xavier Martinet
Marie-Anne Lachaux, Timothee Lacroix, Baptiste Rozière, Naman Goyal
Eric Hambro, Faisal Azhar, Aurelien Rodriguez, Armand Joulin
Edouard Grave*, Guillaume Lample***

params	dimension	n heads	n layers	learning rate	batch size	n tokens
6.7B	4096	32	32	$3.0e^{-4}$	4M	1.0T
13.0B	5120	40	40	$3.0e^{-4}$	4M	1.0T
32.5B	6656	52	60	$1.5e^{-4}$	4M	1.4T
65.2B	8192	64	80	$1.5e^{-4}$	4M	1.4T

Table 2: Model sizes, architectures, and optimization hyper-parameters.



 google/gemma-3-27b-it

 Image-Text-to-Text • Updated Mar 21 • ⬇ 382k • ⚡ • ❤ 1.41k

14 trillion
tokens

 google/gemma-3-27b-pt

 Image-Text-to-Text • Updated Mar 21 • ⬇ 18.8k • ❤ 93

 meta-llama/Llama-4-Scout-17B-16E-Instruct

 Image-Text-to-Text • Updated 11 days ago • ⬇ 287k • ⚡ • ❤ 933

30 trillion
tokens

 meta-llama/Llama-4-Scout-17B-16E

 Image-Text-to-Text • Updated Apr 9 • ⬇ 32.7k • ❤ 173

Access the slides



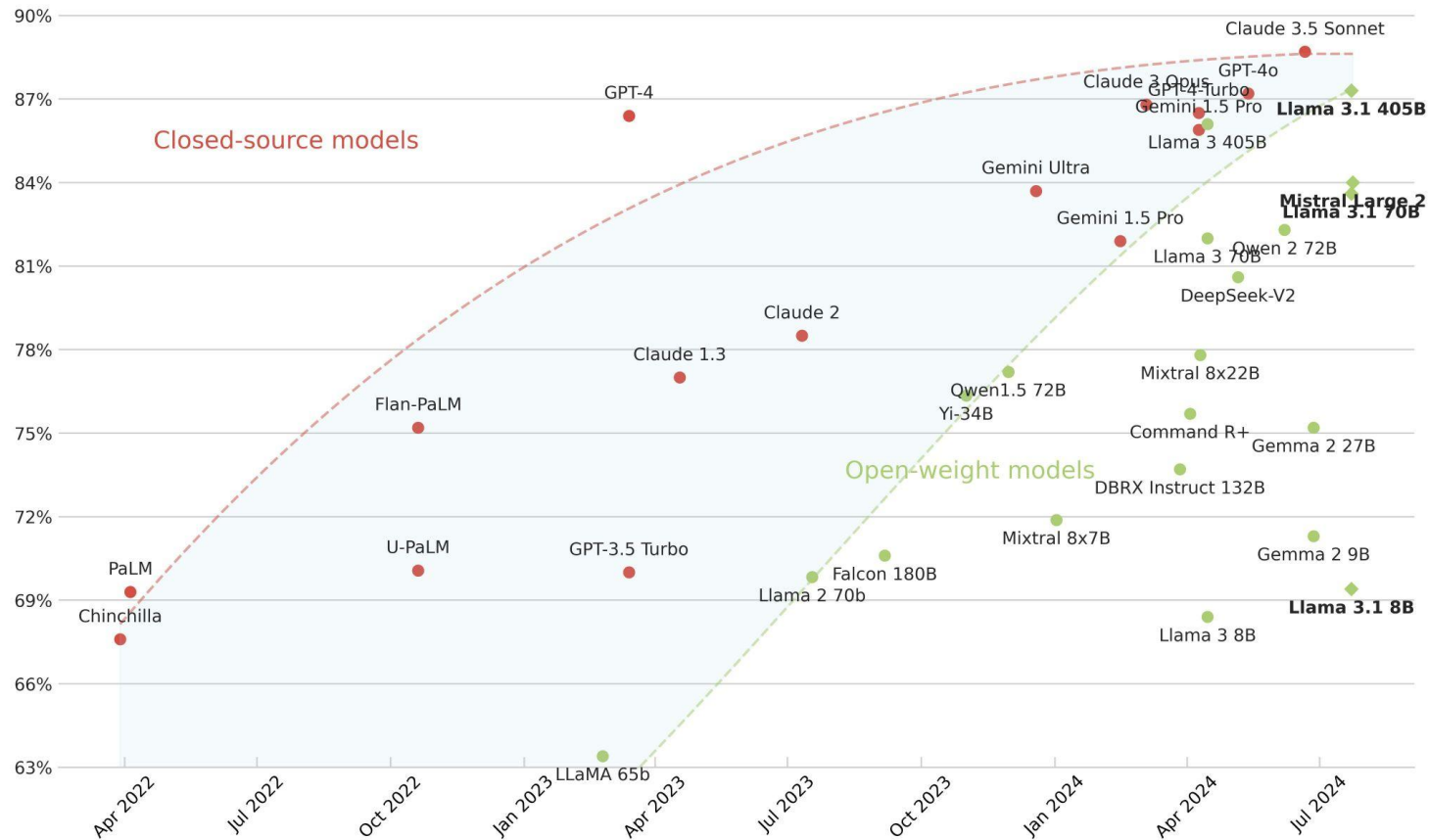
<https://docs.unsloth.ai/ai-engineers-2025>

Closed-source vs. open-weight models

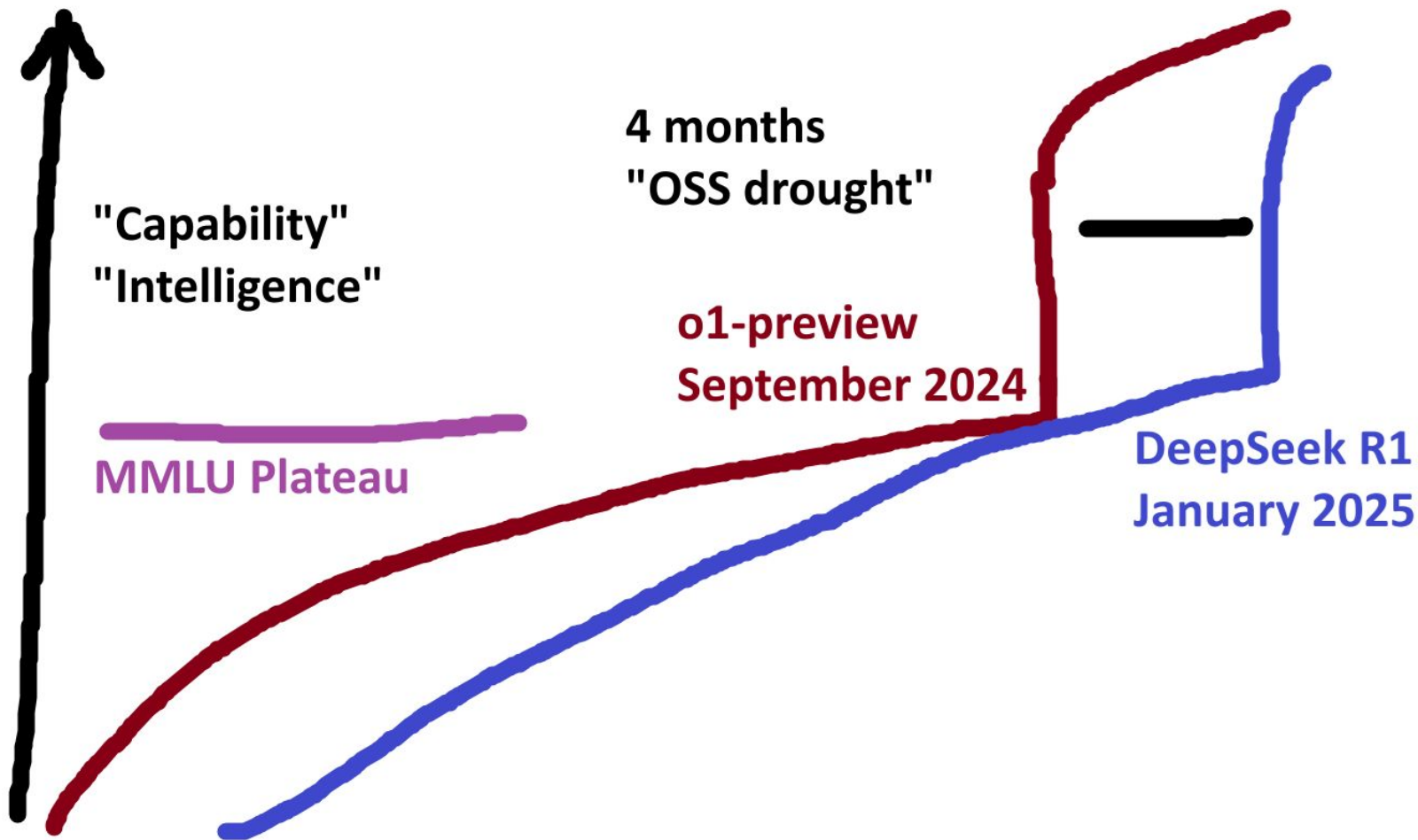
@maximelabonne

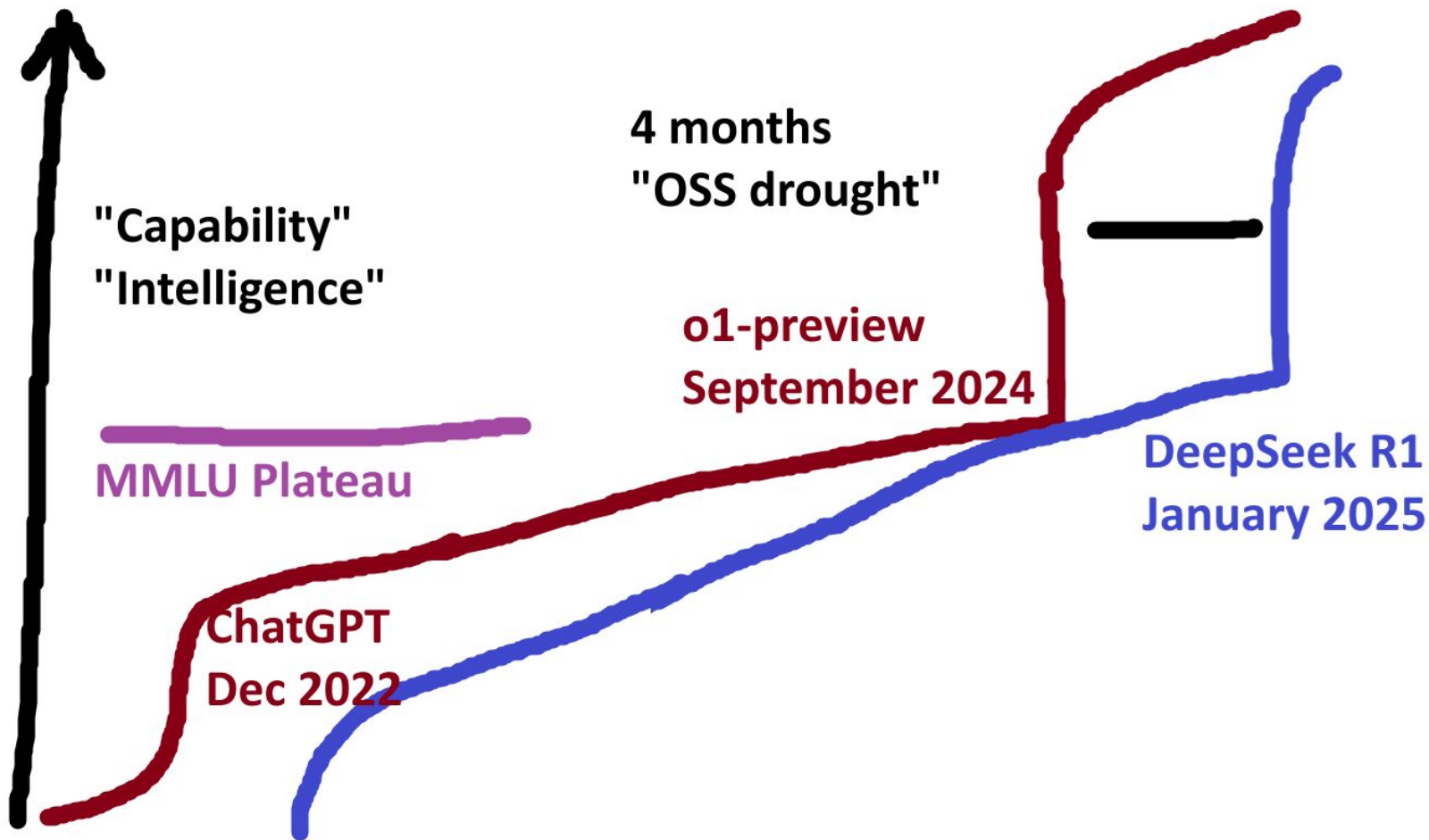
Llama 3.1 405B closes the gap with closed-source models for the first time in history.

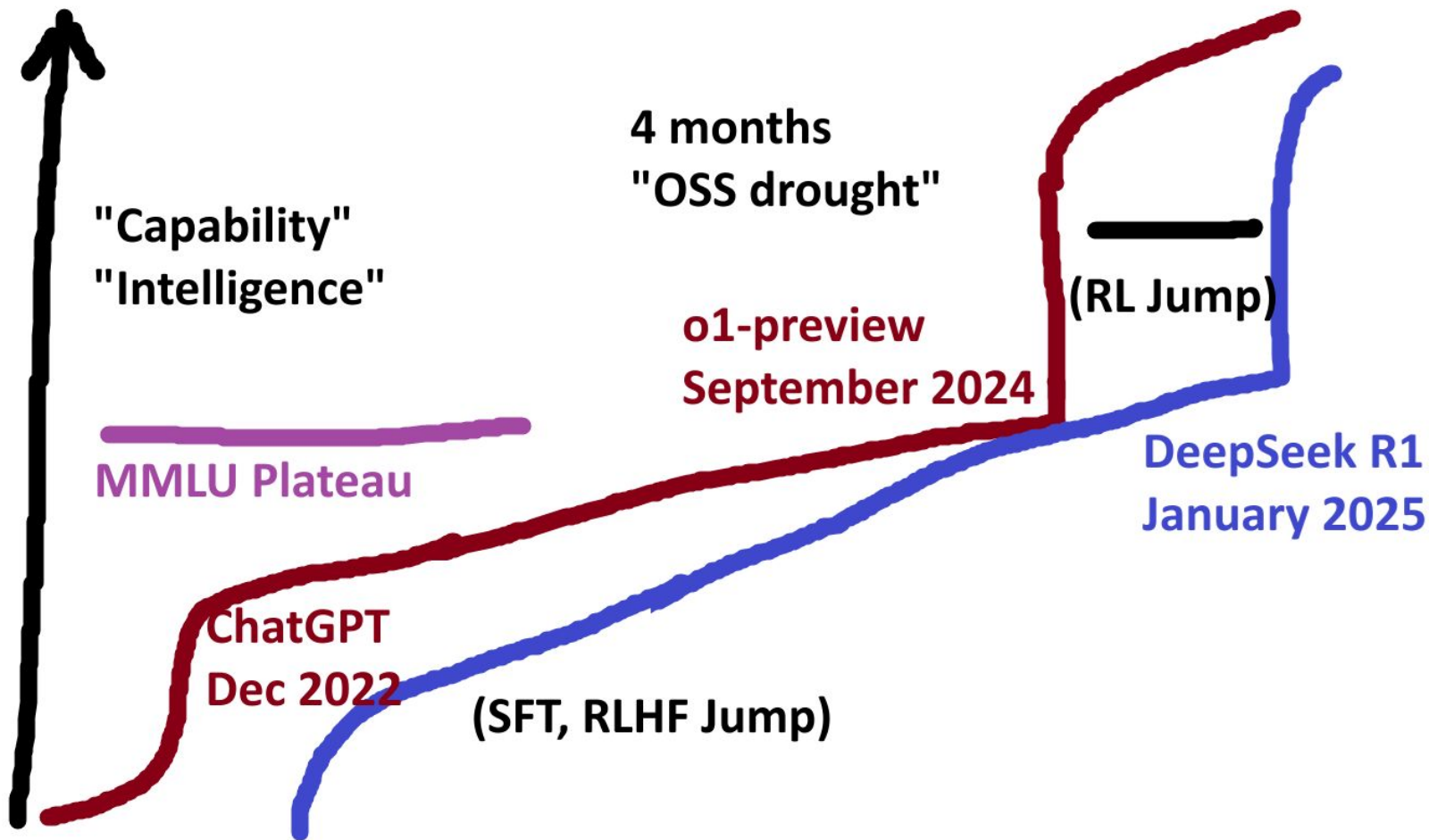
MMLU (5-shot)



<https://x.com/maximelabonne/status/1816416043511808259>







How Much Information Does the Machine Need to Predict?

Y LeCun

Reinforcement Learning (cherry)

- The machine predicts a scalar reward given once in a while.
- **A few bits for some samples**

Supervised Learning (icing)

- The machine predicts a category or a few numbers for each input
- **10→10,000 bits per sample**

Unsupervised Learning (cake)

- The machine predicts any part of its input for any observed part.
- Predicts future frames in videos
- **Millions of bits per sample**



How Much Information is the Machine Given during Learning?

► “Pure” Reinforcement Learning (cherry)

- The machine predicts a scalar reward given once in a while.

► A few bits for some samples

► Supervised Learning (icing)

- The machine predicts a category or a few numbers for each input
- Predicting human-supplied data
- 10→10,000 bits per sample

► Self-Supervised Learning (cake génoise)

- The machine predicts any part of its input for any observed part.
- Predicts future frames in videos
- Millions of bits per sample



Deep Learning and the Future of AI September 2016!!!

https://youtu.be/_1Cyyt-4-n8?si=UdDAB5bkhqJs68pz&t=3717

Training Stages



GPT 4 Base
Claude 4 Base
Gemini Base

GPT 4 / ChatGPT 4
Claude 4 Opus
Gemini 2.5 Pro

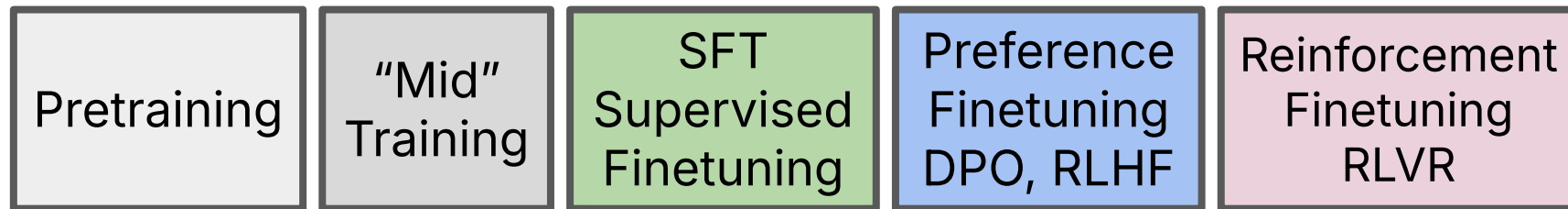
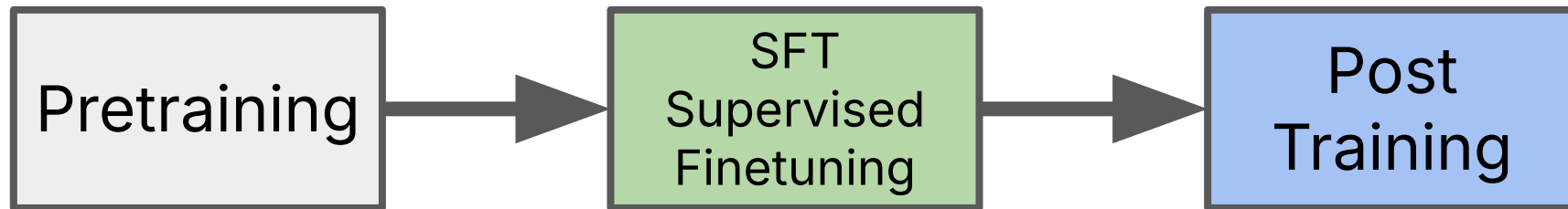
Training Stages

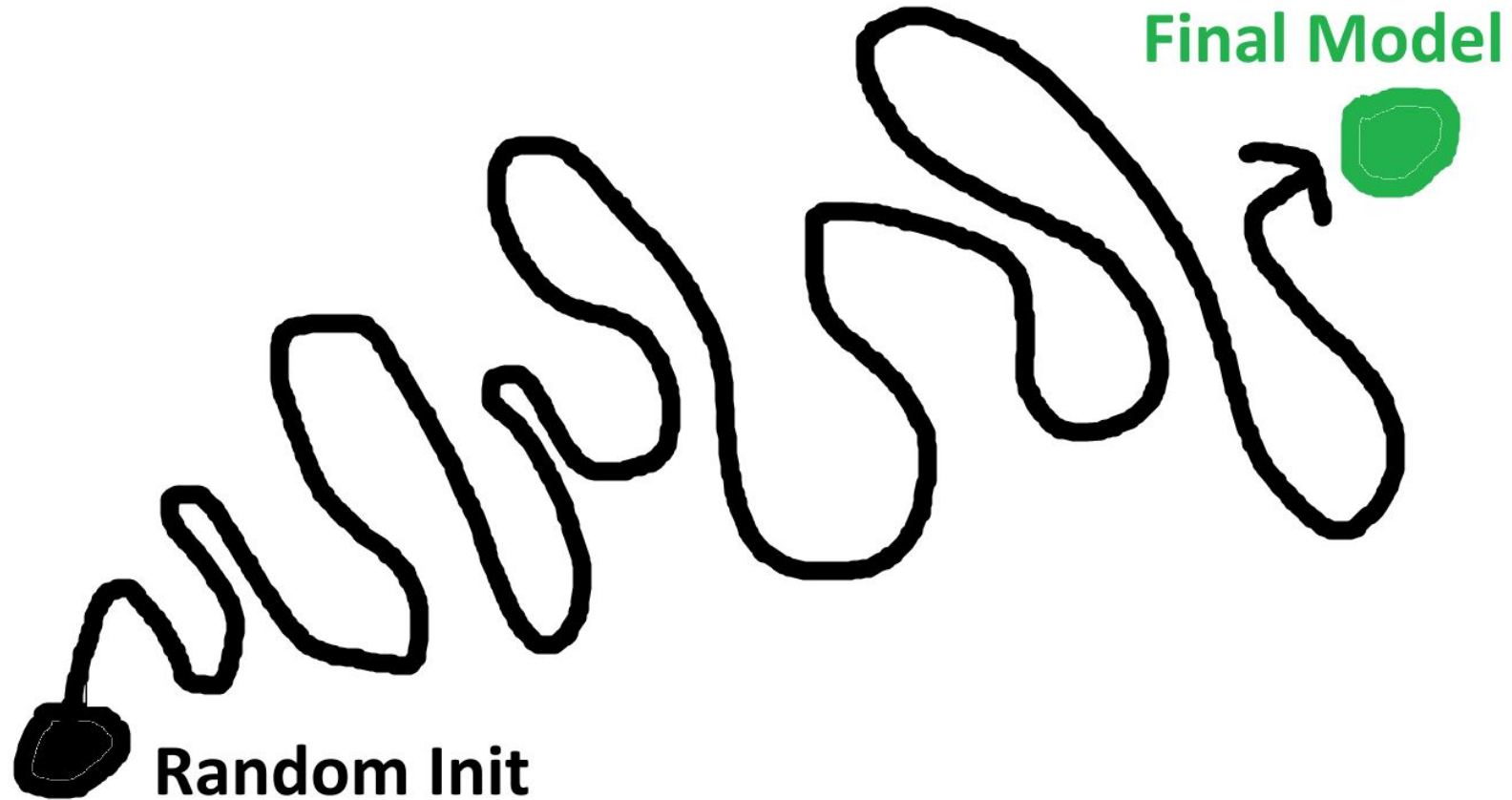


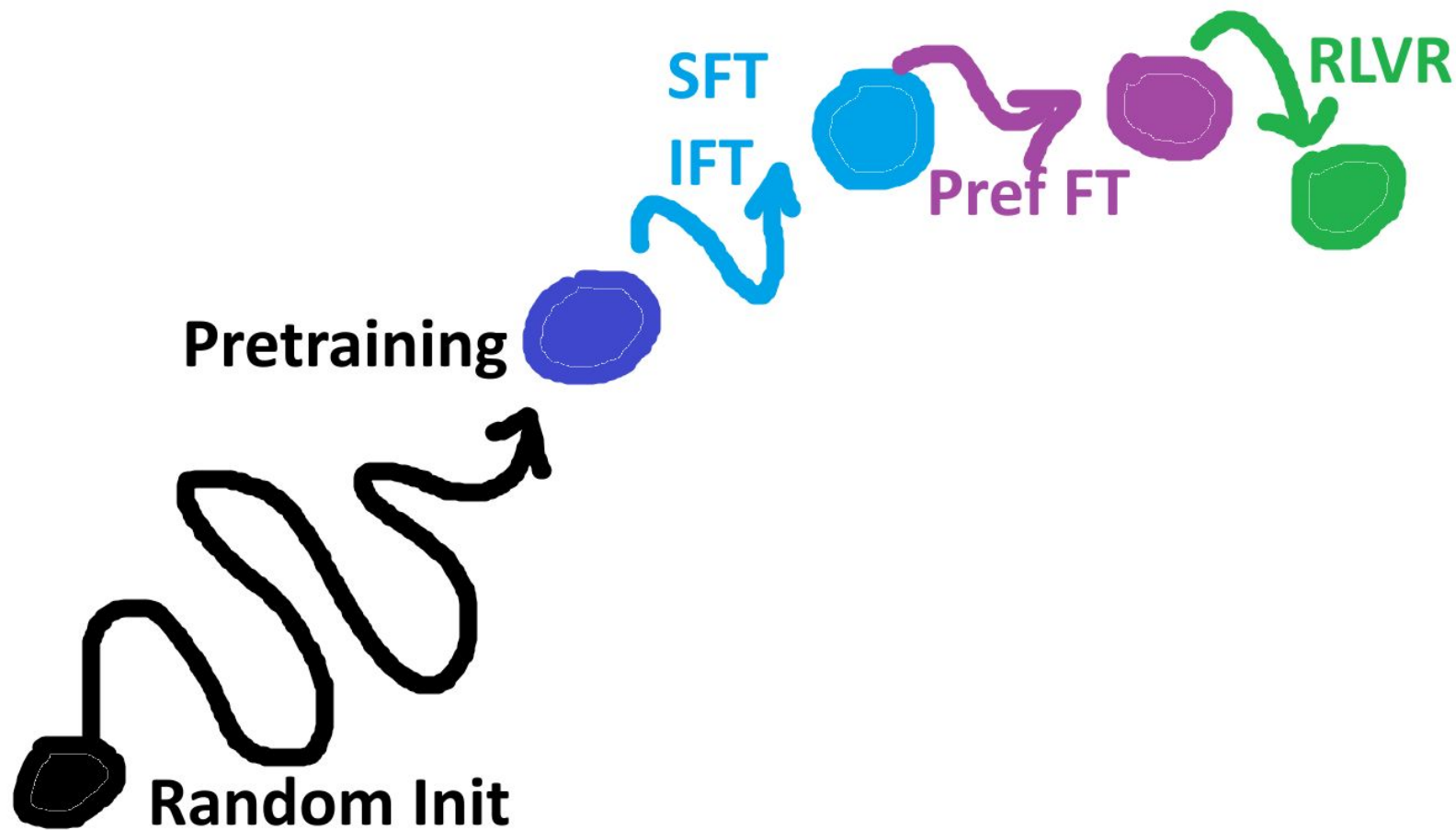
Gemma 3 PT
Llama 4
Qwen 3 Base
Mistral Small Base
Llama 2

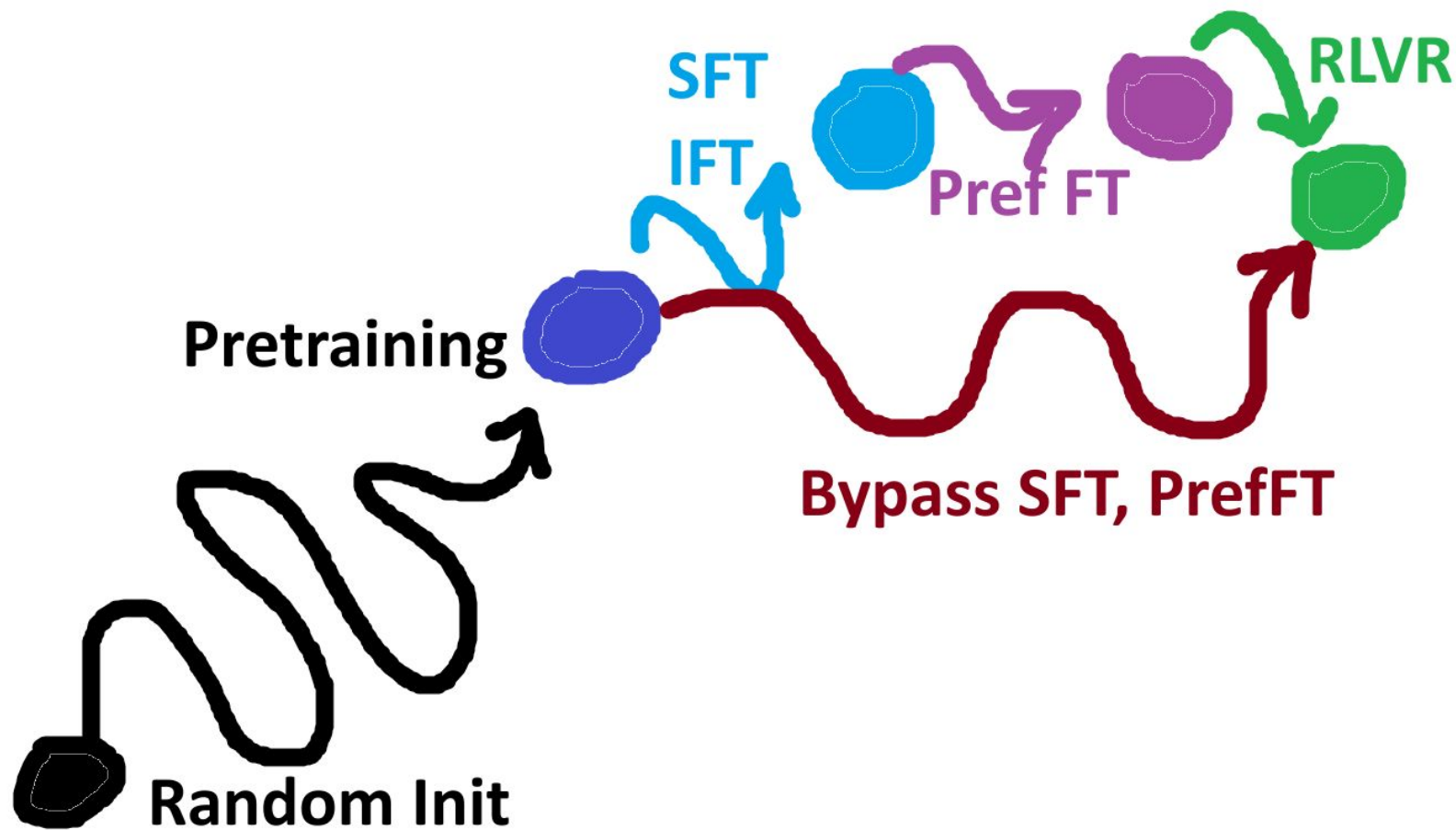
Gemma 3 IT
Llama 4 Instruct
Qwen 3
Mistral Small Instruct
Llama 2 Chat

Finetuning everywhere

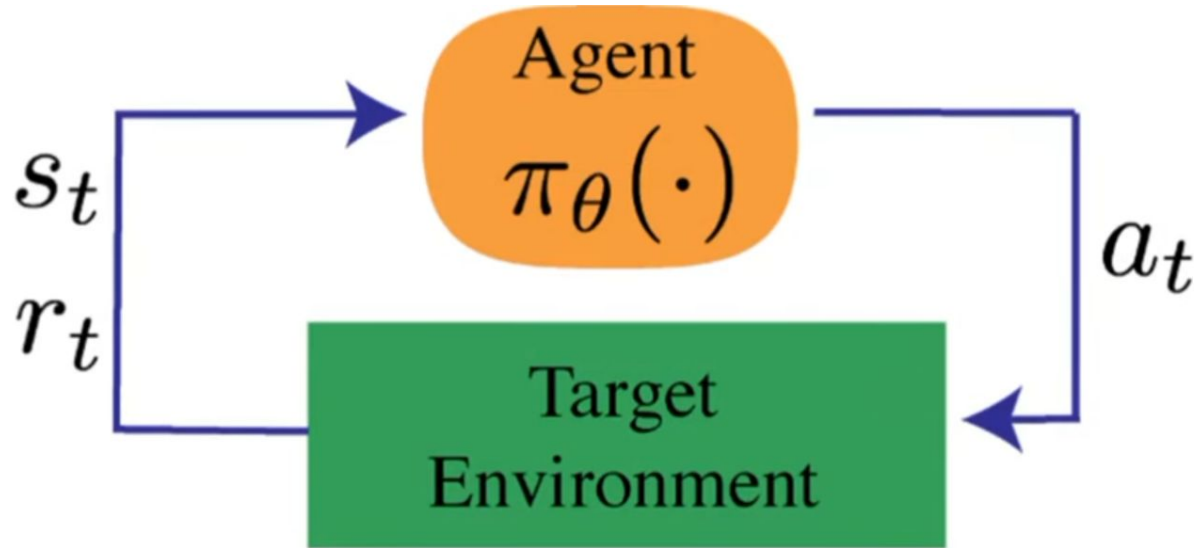








Agents in the old sense



Some notation:

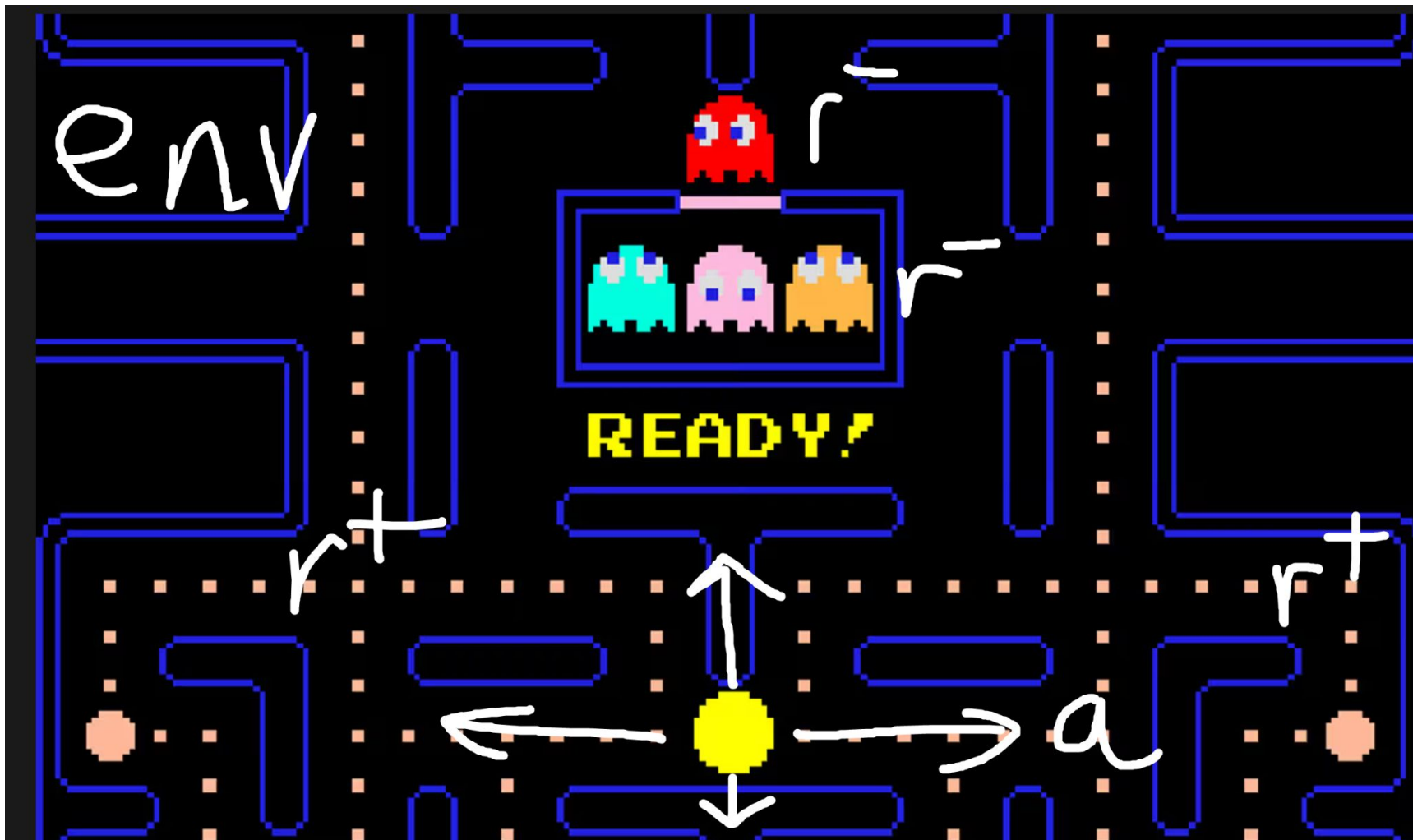
s_t : state

r_t : reward

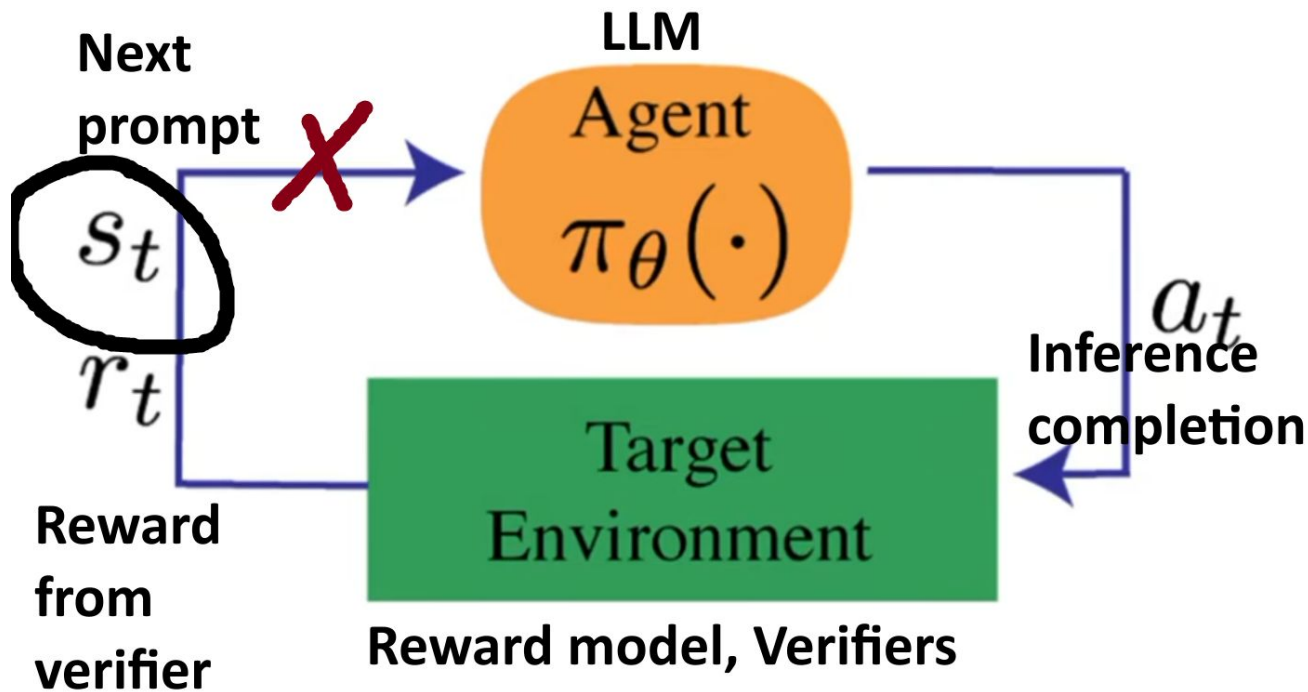
a_t : action

$a_t \sim \pi_{\theta}(s_t)$: policy

<https://youtu.be/zYelqzULzr0?si=RawclaFMYwL7xPrU> **Experimenting with Reinforcement Learning with Verifiable Rewards (RLVR) Nathan Lambert**



Reinforcement Learning for LLMs



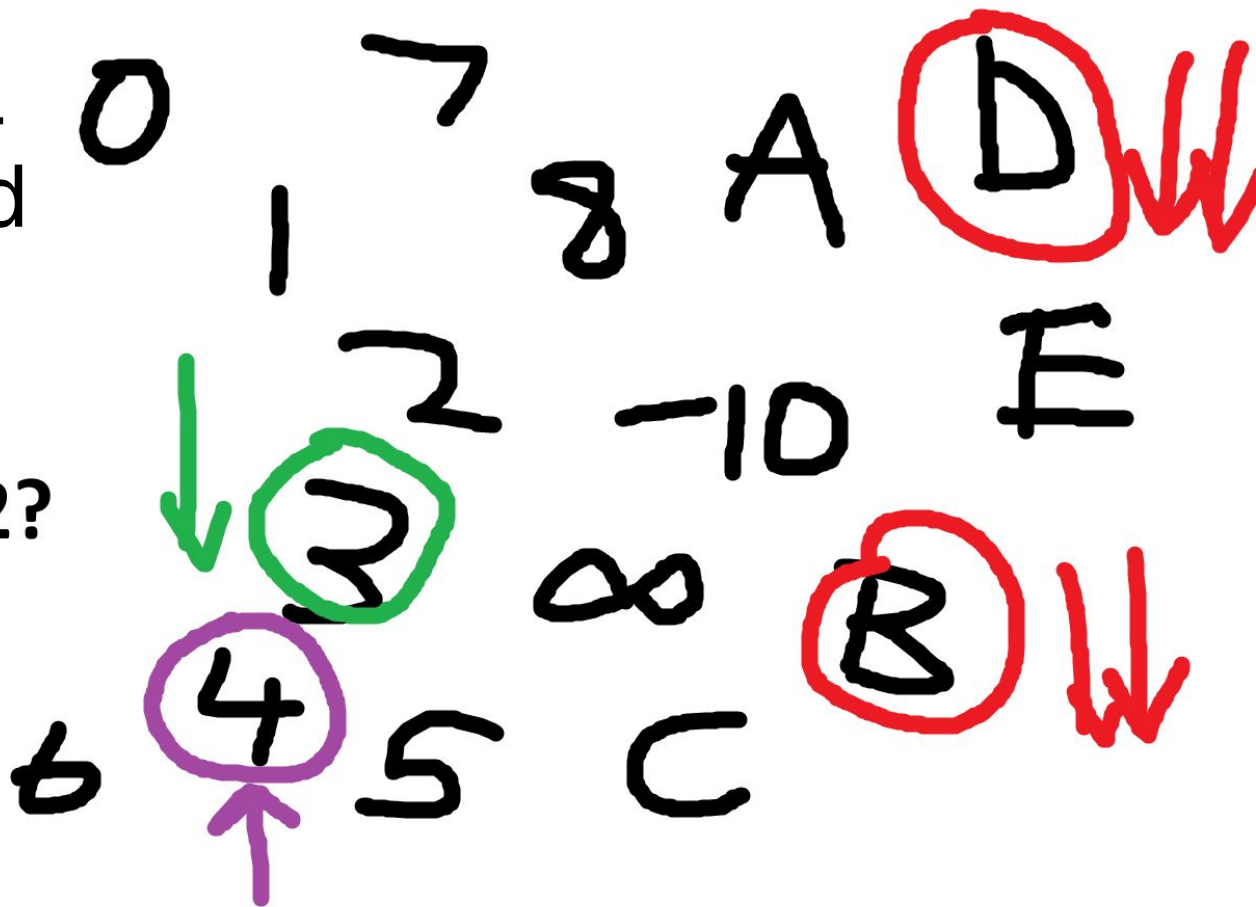
S

What is $2+2$?

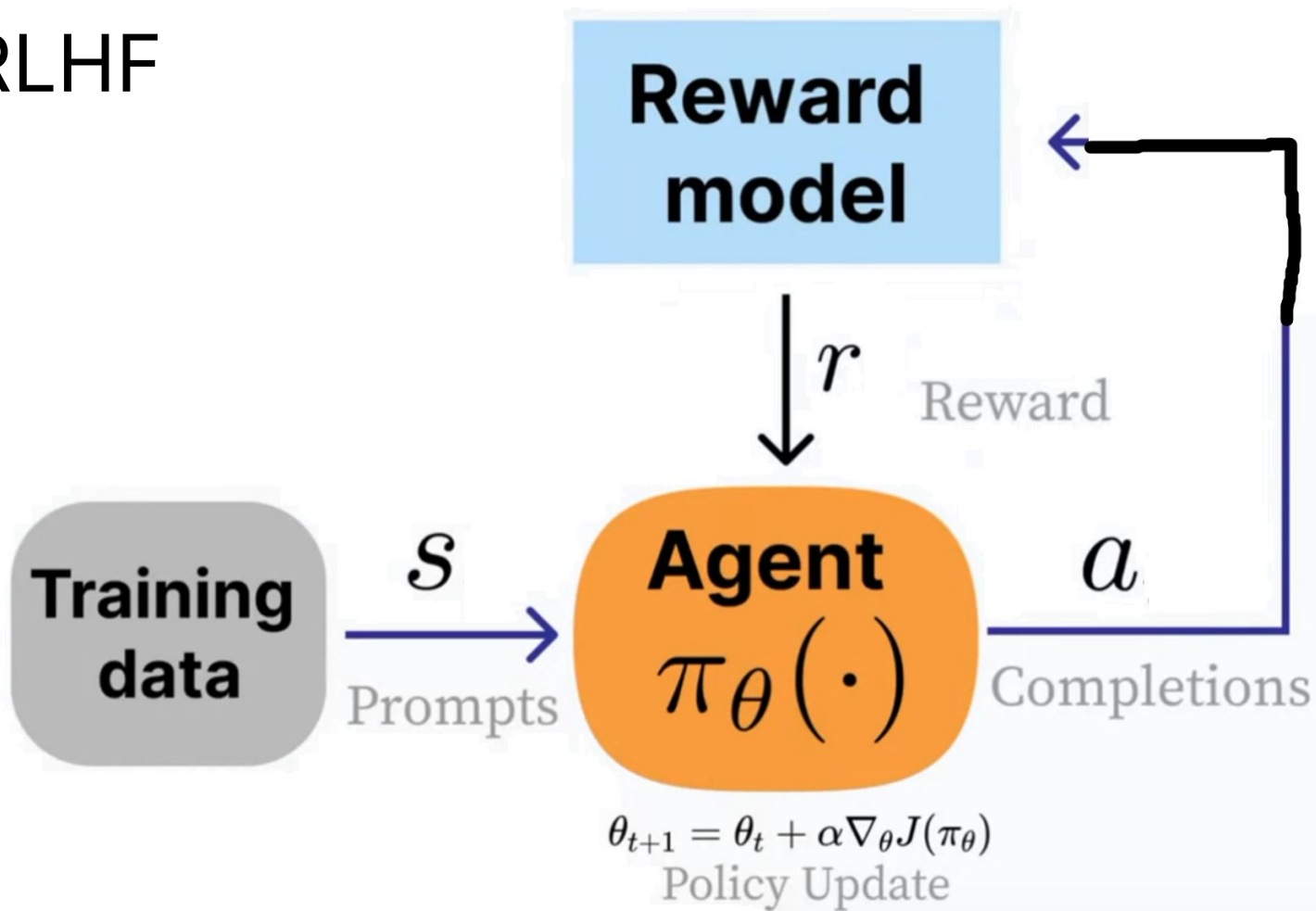
0 7 8 A D
1 2 -10 E
3 4 5 6 7 8 9
+1 C B a

Goal of RL
More good
Less bad

What is $2+2$?



RLHF



PPO

**Reward
model**

Completions

a

r

Reward

**Training
data**

S

Prompts

Agent $\pi_{\theta}(\cdot)$



**Generating
Policy**



**Reference
Policy**



**Value
Model**

$\theta_{t+1} = \theta_t + \alpha \nabla_{\theta} J(\pi_{\theta})$
Policy Update

GRPO

**Reward
model**

Completions

a

r

Reward

**Training
data**

S

Prompts

Agent $\pi_{\theta}(\cdot)$



**Generating
Policy**



**Reference
Policy**

$\theta_{t+1} = \theta_t + \alpha \nabla_{\theta} J(\pi_{\theta})$
Policy Update

GRPO
+
RLVR

**Ground Truth
Reward**

$$r = \begin{cases} 1 & \text{if correct} \\ 0 & \text{otherwise} \end{cases}$$

Completions

a



r

Reward

**Training
data**

S

Prompts

Agent $\pi_{\theta}(\cdot)$



**Generating
Policy**



**Reference
Policy**

$$\theta_{t+1} = \theta_t + \alpha \nabla_{\theta} J(\pi_{\theta})$$

Policy Update

LLM as a judge
Regex check
Format check
Executable code

**Ground Truth
Reward**

$$r = \begin{cases} 1 & \text{if correct} \\ 0 & \text{otherwise} \end{cases}$$

Completions

a



r

Reward

**Training
data**

S

Prompts

Agent $\pi_{\theta}(\cdot)$



Generating
Policy



Reference
Policy

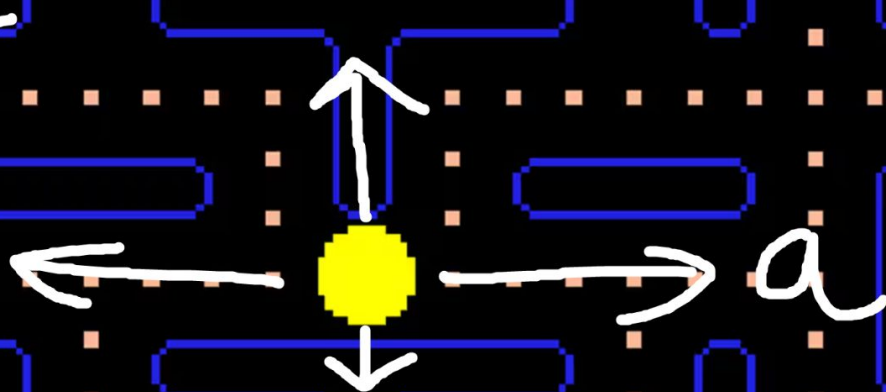
$$\theta_{t+1} = \theta_t + \alpha \nabla_{\theta} J(\pi_{\theta})$$

Policy Update

env

Can't
Know
"Best"
action

READY!



Maximize

$$\nabla_{\theta} J(\pi_{\theta}) = \mathbb{E}_{\tau} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) R_t \right]$$

Action given state

$$\nabla_{\theta} J(\pi_{\theta}) = \mathbb{E}_{\tau} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) R_t \right]$$

Total Gradient

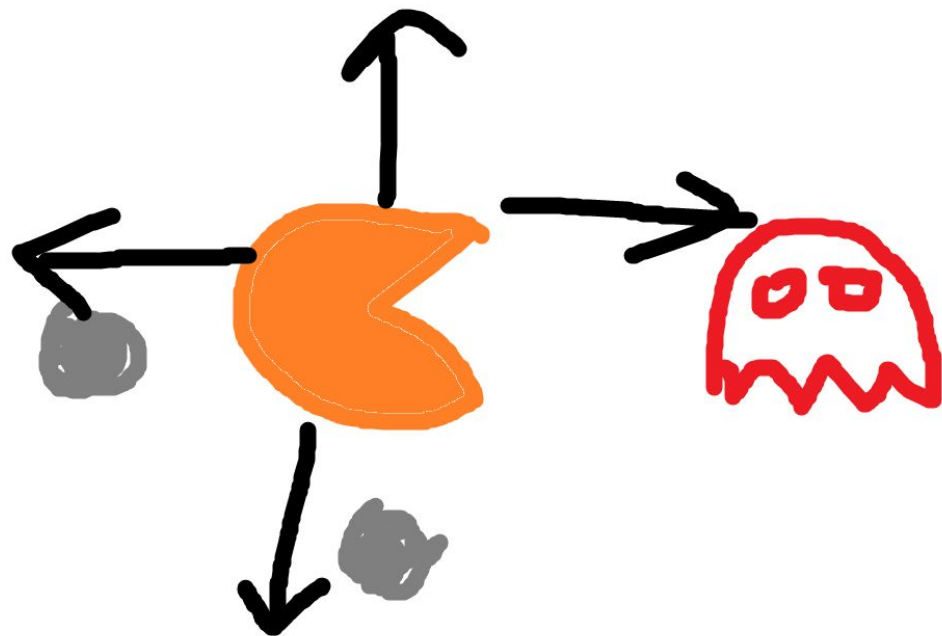
"Calculate gradient"

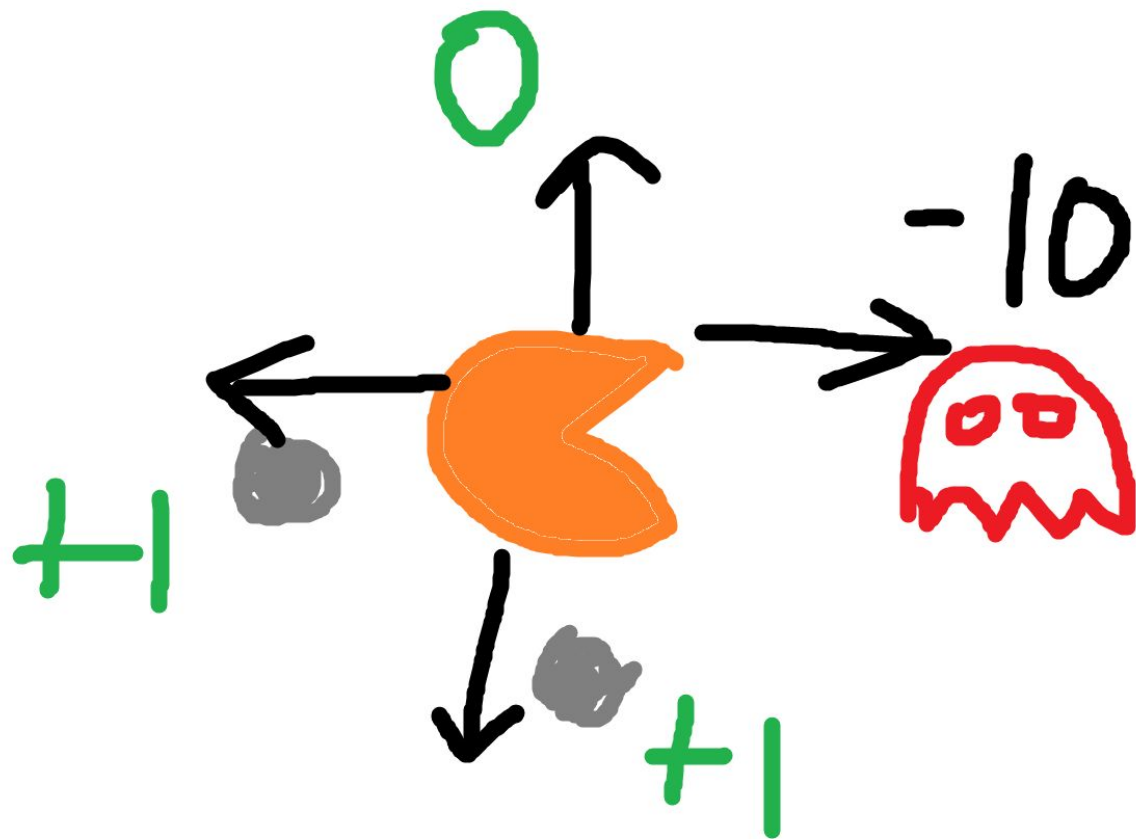
Policy LLM

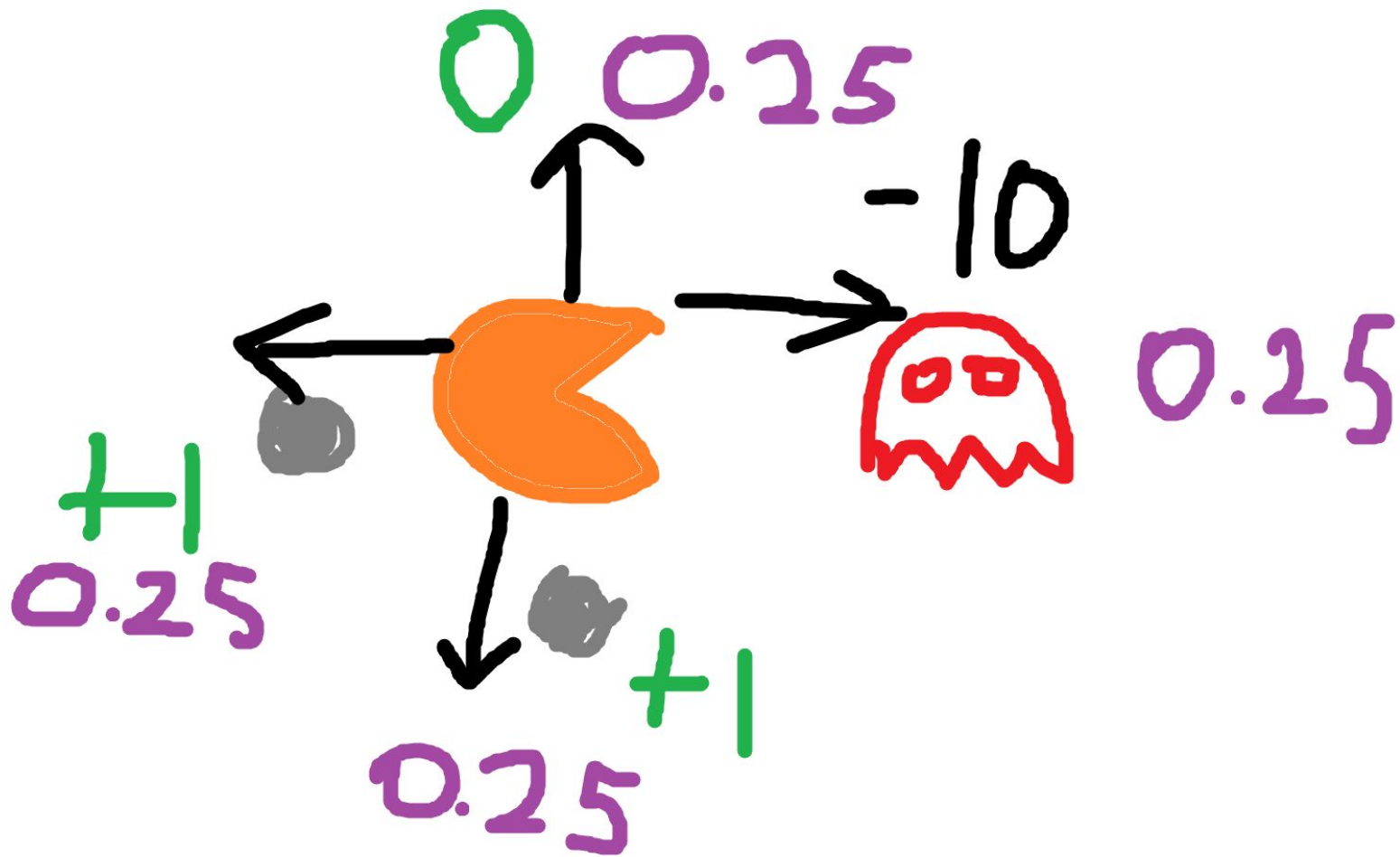
Reward

Maximize

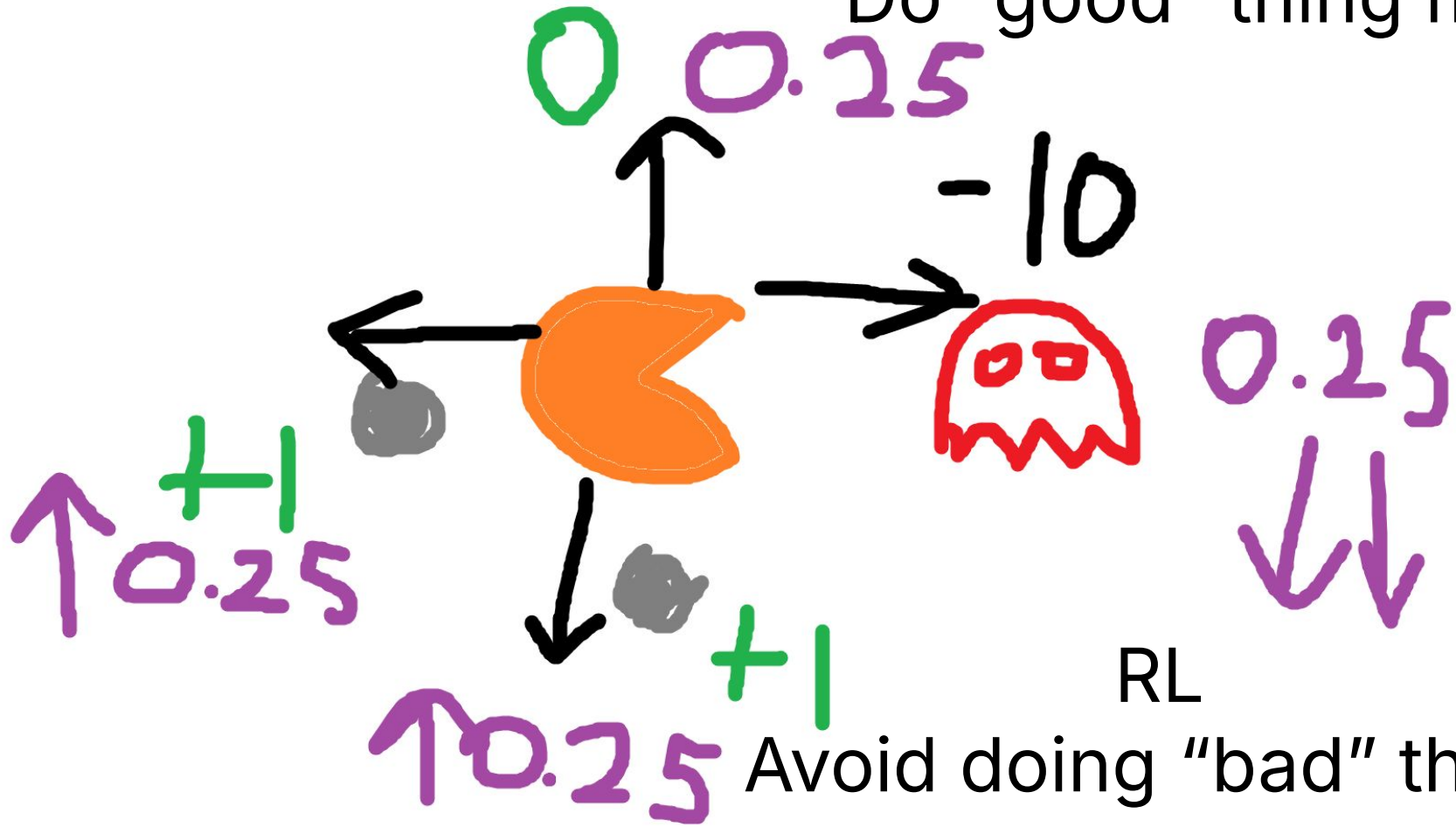
$$\frac{d}{dW} \log P(\text{action}|\text{state}) \cdot \text{reward}$$







Do "good" thing more



Avoid doing "bad" thing

	$P(\text{action} \text{state})$	Reward	$P(A S)*\text{Reward}$	$(\log P)*R$
Up	0.25	0	0	0
Down	0.25	1	0.25	-0.6020599
Left	0.25	1	0.25	-0.6020599
Right	0.25	-10	-2.5	6.0205999
				4.8164799

	P(action state)	Reward	P(A S)*Reward	(logP)*R
Up	0.2	0	0	0
Down	0.2	1	0.2	-0.69897000
Left	0.2	1	0.2	-0.69897000
Right	0.4	-10	-4	3.97940000
				2.58146000

	P(action state)	Reward	P(A S)*Reward	(logP)*R
Up	0.3	0	0	0
Down	0.3	1	0.3	-0.52287877
Left	0.3	1	0.3	-0.52287877
Right	0.1	-10	-1	10
				8.95424250

REINFORCE

Advantage = Normalized Reward
from "baseline"

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t \mid s_t) A_t \right]$$

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t \mid s_t) (G_t - \underline{b}) \right]$$

Value Function / Model

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) (G_t - \underline{b}) \right]$$

Estimates

What is the **average reward** if we see the current state

Value Function / Model

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) (G_t - \underline{b}) \right]$$

$A < 0$ if "worse" than average

$A > 0$ if "better" than average

Do action more better than average

Proximal Policy Optimization

Maximize $J()$

$$J(\theta) = \min \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A \right).$$

Proximal Policy Optimization

$$J(\theta) = \min \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A \right).$$

$$J(\theta) = \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A \right).$$

Proximal Policy Optimization

What we want to maximize

$$J(\theta) = \min \left(\underbrace{\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A \right)$$

**Model that
created action**

Maximize Likelihood ratio

Proximal Policy Optimization

Top	Bot	Top/Bot	
0.01	0.01	1	
0.01	0.99	0.01	Likely, but we do not want
0.99	0.01	99	Not likely, but we want
0.99	0.99	1	

Proximal Policy Optimization

If we just maximize will “reward hack”

What is $2+2$?

To solve this question, we need to ...

...

Hello Hello Hello Hello ← NOT LIKELY

4 ← Correct answer though

Proximal Policy Optimization

$$J(\theta) = \min \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, \underbrace{1 - \varepsilon, 1 + \varepsilon} \right) A \right)$$

"Trust region"

Do not trust large gradient updates

Eps = 0.1, 0.2, 0.3

1-E = 0.8, 1+E=1.2

PPO - KL term

**Deviation from
SFT model**

KL Divergence

$$r_t = r_{\varphi}(q, o_{\leq t}) - \beta \log \frac{\pi_{\theta}(o_t | q, o_{< t})}{\pi_{ref}(o_t | q, o_{< t})}$$

Beta = 0.05

Deviates too much = bad, so like a "tax"

Proximal Policy Optimization

Maximize $J()$

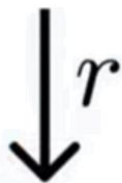
$$J(\theta) = \min \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)} A, \text{clip} \left(\frac{\pi_{\theta}(a|s)}{\pi_{\theta_{old}}(a|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A \right).$$

GRPO
Remove
Value
Model

**Reward
model**

Completions

a



r

Reward

**Training
data**

S

Prompts

Agent $\pi_{\theta}(\cdot)$



**Generating
Policy**



**Reference
Policy**

$\theta_{t+1} = \theta_t + \alpha \nabla_{\theta} J(\pi_{\theta})$
Policy Update

Group Relative Policy Optimization

Value model to estimate base /
"average" rewards removed

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) (G_t - \underline{b}) \right]$$

Do action more better than average

Do "rollout" ie inference sampling

What is 2+2?

.	.	.	.	0
.	.	.	.	1
.	.	.	.	2
.	.	.	.	4

Take statistics

What is 2+2?

.	.	.	.	0	0
.	.	.	.	1	0
.	.	.	.	2	0
.	.	.	.	4	1

Take statistics
Advantage = Z Score
No more value model!

$$A_i = \frac{r_i - \text{mean}(r_1, r_2, \dots, r_G)}{\text{std}(r_1, r_2, \dots, r_G)}$$

Taking Z Scores

What is 2+2?	Prediction	Reward	Mean	Std	(R-M)/S
	0	0			-0.866
	1	0			-0.866
	2	0			-0.866
	4	1			1.443
			0.375	0.43301	

Why "Group Relative"?

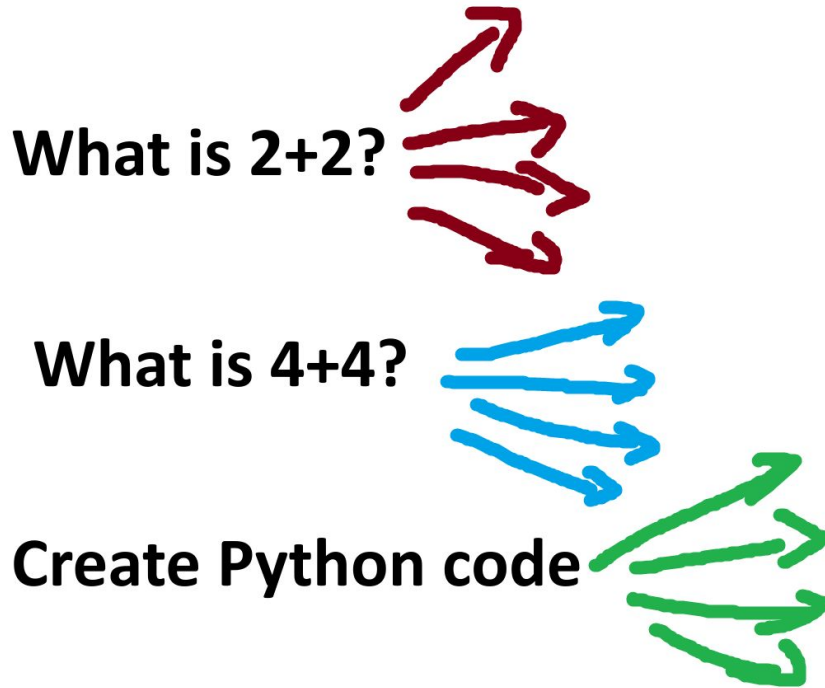
What is 2+2?	Prediction	Reward	Mean	Std	(R-M)/S
	0	0			-0.866
	1	0			-0.866
	2	0			-0.866
	4	1			1.443
			0.375	0.43301	

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Why "Group Relative"?



GRPO full form

$$J(\theta) = \frac{1}{G} \sum_{i=1}^G \left(\min \left(\frac{\pi_{\theta}(a_i|s)}{\pi_{\theta_{old}}(a_i|s)} A_i, \text{clip} \left(\frac{\pi_{\theta}(a_i|s)}{\pi_{\theta_{old}}(a_i|s)}, 1 - \varepsilon, 1 + \varepsilon \right) A_i \right) - \beta D_{KL}(\pi_{\theta} || \pi_{ref}) \right)$$

Resources

<https://rlhfbook.com/c/11-policy-gradients.html>

https://www.youtube.com/watch?v=bAWV_yrqx4w

Colab GRPO Notebook

[https://colab.research.google.com/github/unslothai/notebooks/blob/main/nb/Qwen3_\(4B\)-GRPO.ipynb](https://colab.research.google.com/github/unslothai/notebooks/blob/main/nb/Qwen3_(4B)-GRPO.ipynb)

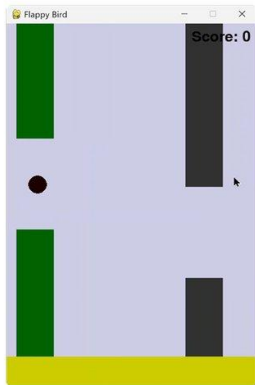
🌟 Finetune for Free

Notebooks are beginner friendly. Read our [guide](#). Add your dataset, click "Run All", and export your finetuned model to GGUF, Ollama, vLLM or Hugging Face.

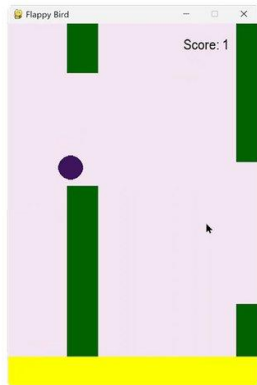
Unsloth supports	Free Notebooks	Performance	Memory use
Qwen3 (14B)	▶ Start for free	2x faster	70% less
Qwen3 (4B): GRPO	▶ Start for free	2x faster	80% less

deepseek R1

Dynamic 1.58-bit GGUF



R1 original 8-bit



R1 dynamic 1-bit

To test the quantized models, we asked DeepSeek R1 to create a Flappy Bird game with 3 tries (pass@3), scoring it on 10 criteria (e.g., random colors, shapes, and Python compatibility). We used seeds 3407, 3408, and 3409, with a temperature of 0.6.

The left is from chat.deepseek.com, the right is 1.58bit. As you can see, the 1.58bit's code executes a fully functional Flappy Bird game. 1.58bit runs at ~140 tokens/sec with 160GB VRAM.



R1-0528

Dynamic 1-bit GGUFs



Qwen3

Support includes R1-0528
Qwen3-8B Distill GGUFs

Naive quantization causes the model to break with loops, gibberish and produce poor code. Our dynamic quantizers solve this.

By studying R1-0528's architecture, we selectively quantize layers to higher bits (like 4-bit), and layers like MOE to lower bits.

The 1.78-bit quant can fit in 1x 24GB VRAM GPU with offloading for fast generation inference at ~10 tokens/sec.

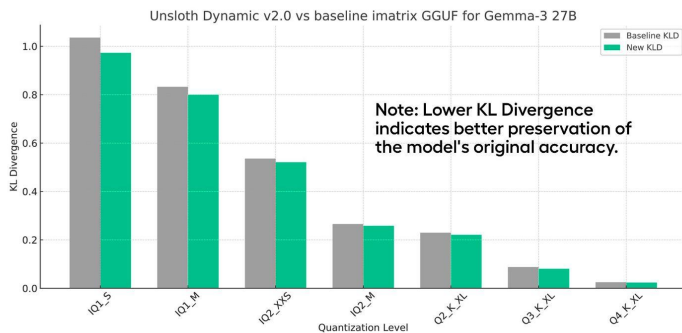
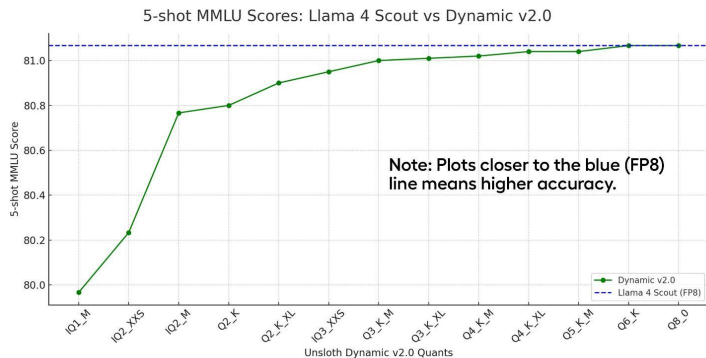


unloth

Dynamic v2.0 GGUF

deepseek R1 ∞ Llama 4 Gemma 3

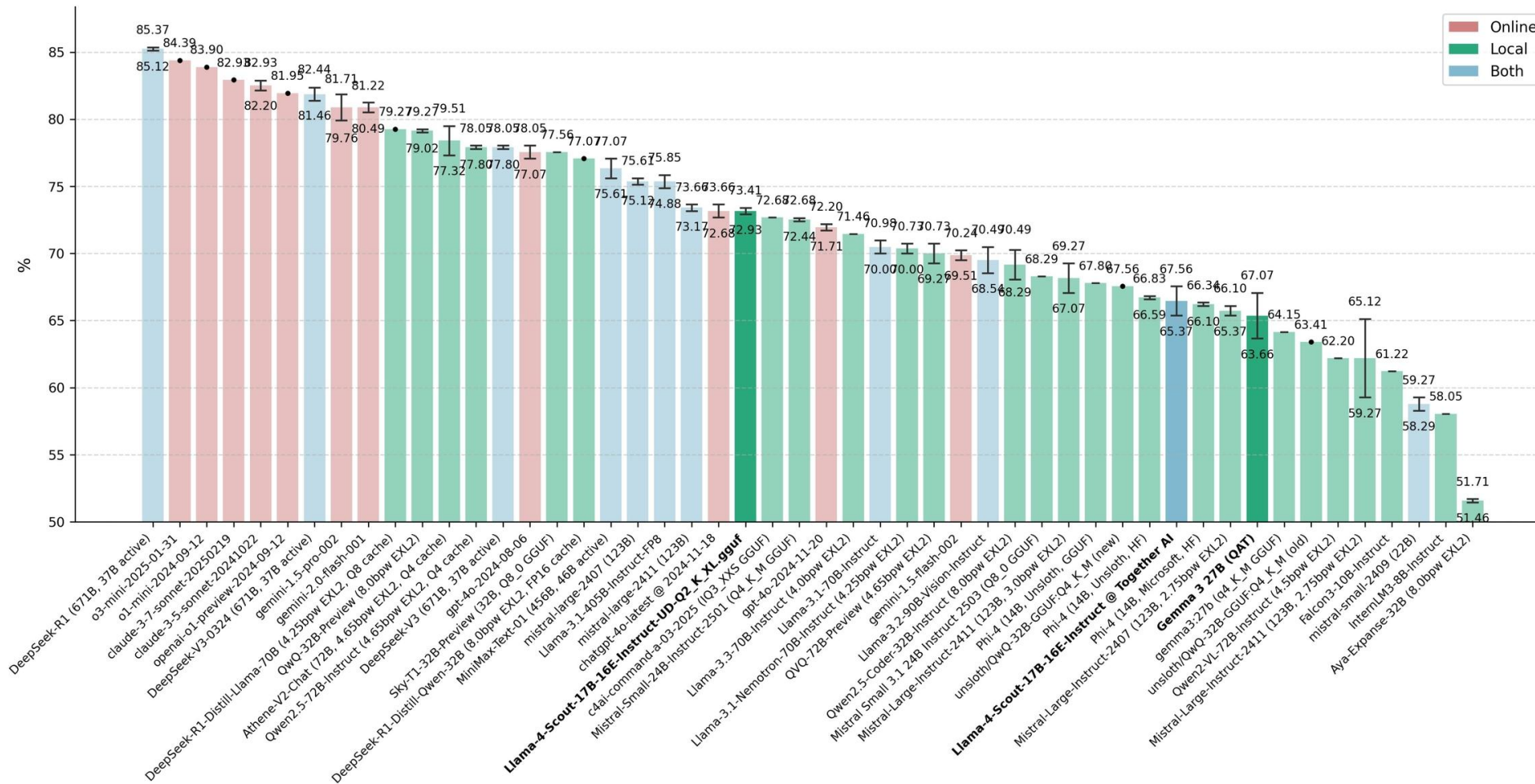
You can now run quantized LLMs while preserving as much accuracy as possible via our revamped selective layer quantization + calibration dataset.



Quantize MoE layers heavily

Leave attention Shared experts In higher precision

Wolfram Ravenwolf's MMLU-Pro Computer Science LLM Benchmark Results (2025-04-08)

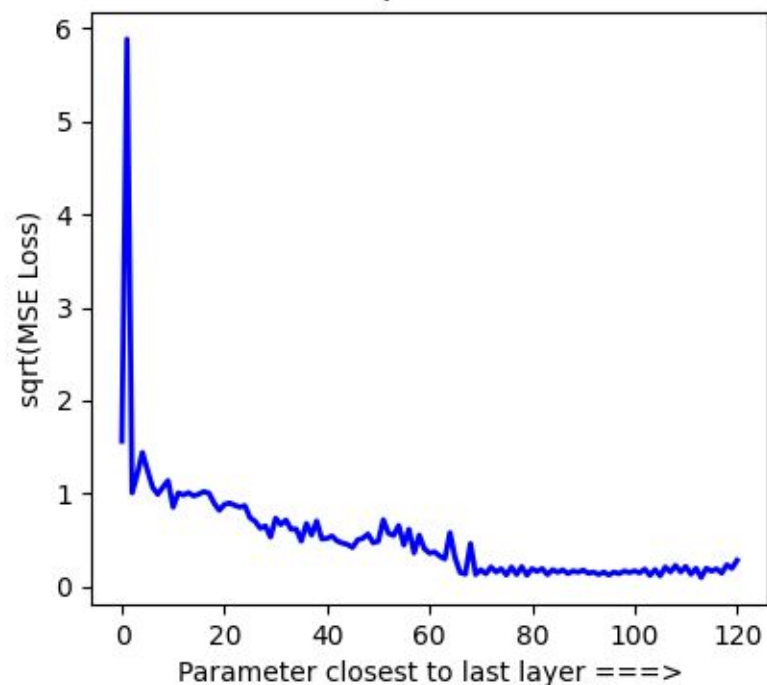




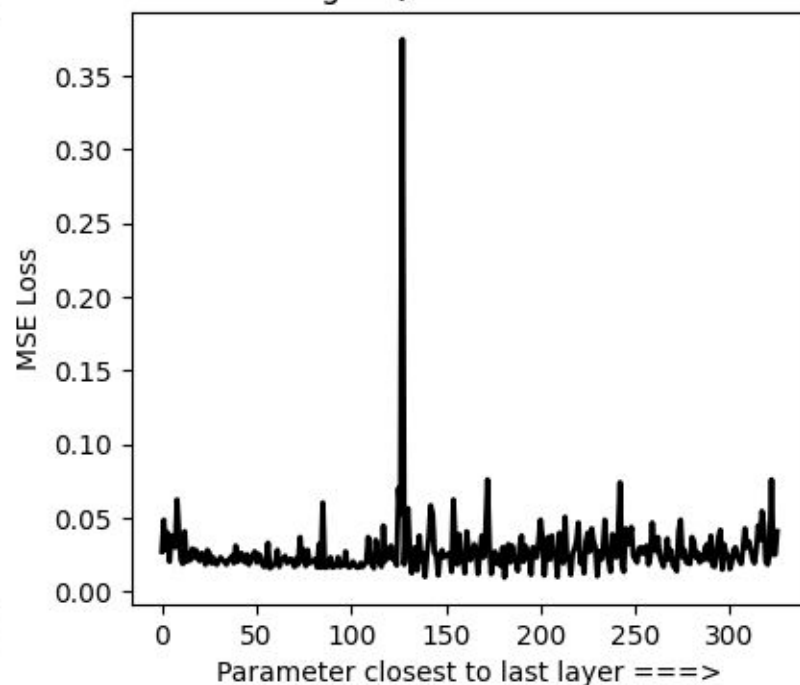
Qwen2-VL-2B-Instruct	Description	Size	Result
16bit	The image shows a train traveling on tracks.	4.11GB	✓
Default 4bit all layers	The image depicts a vibrant and colorful scene of a coastal area.	1.36GB	✗
Unsloth quant	The image shows a train traveling on tracks.	1.81GB	✓

Qwen2-VL-2B-Instruct Quantization Errors

Activation Quantization Error

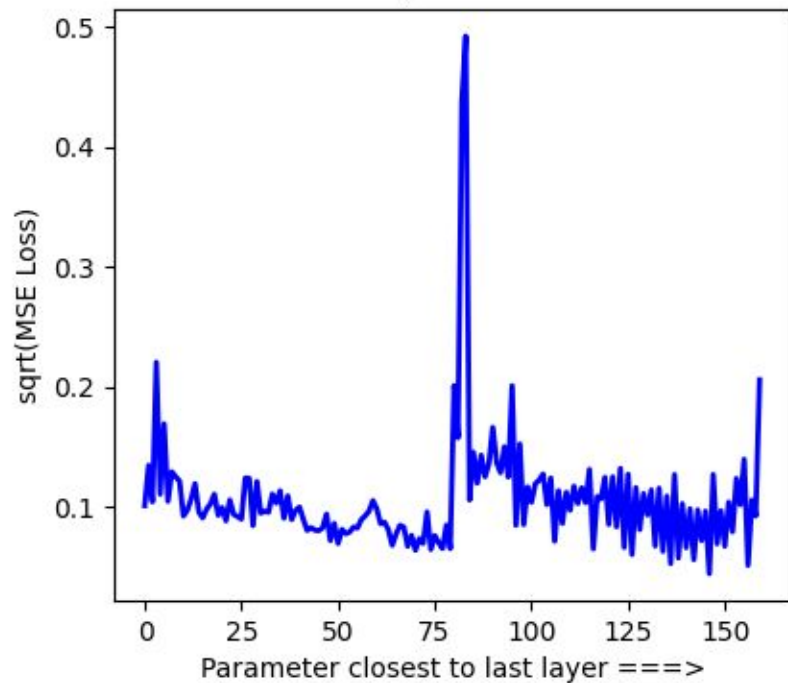


Weight Quantization Error

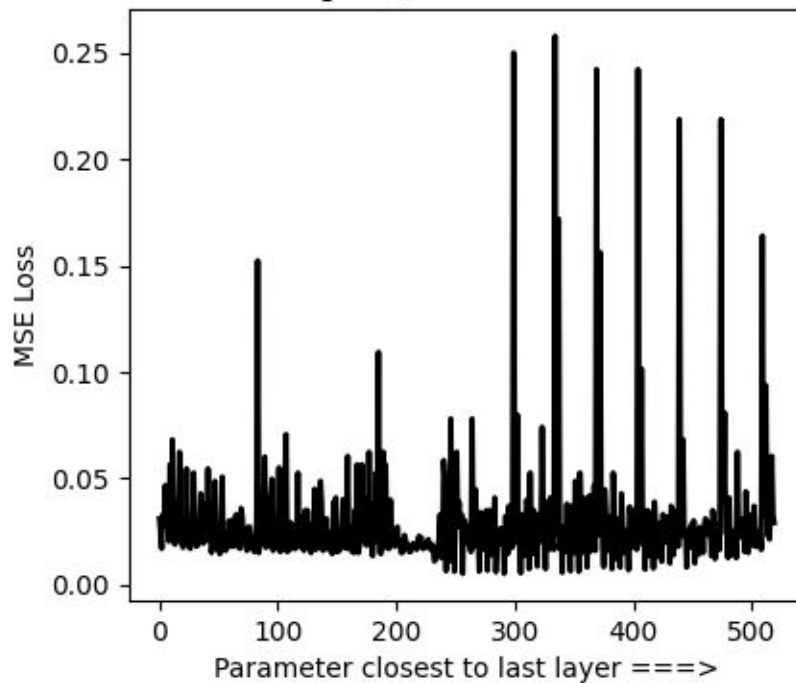


Llama-3.2-11B-Vision-Instruct Quantization Errors

Activation Quantization Error

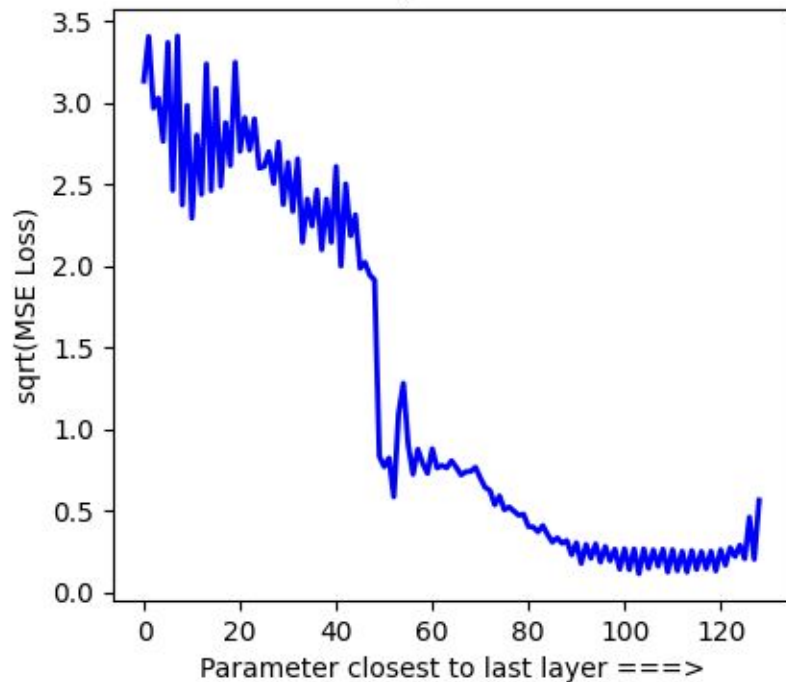


Weight Quantization Error

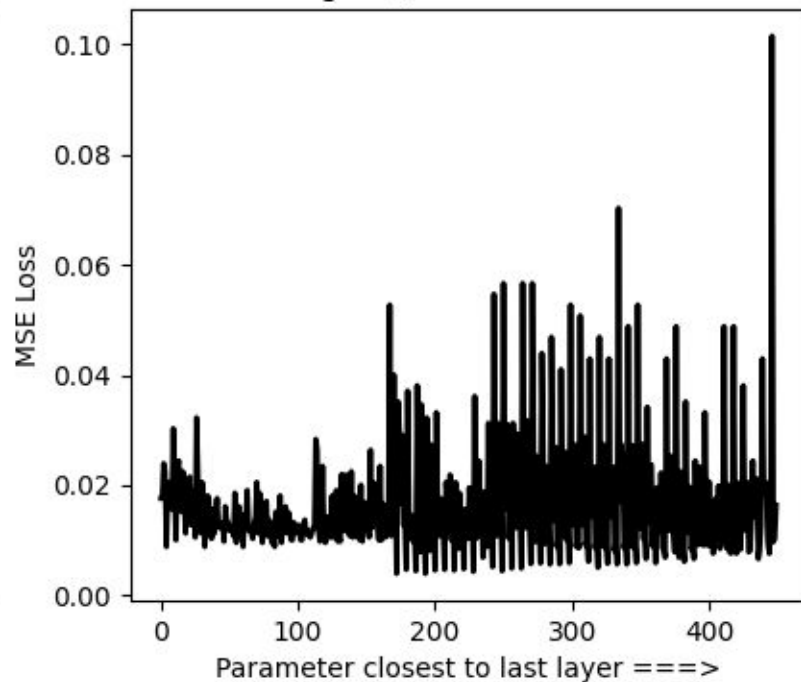


Pixtral-12B-2409 Quantization Errors

Activation Quantization Error



Weight Quantization Error



Model	No.	Type	Weight	Coordinates
Llama 7B	2	mlp	down_proj	[3968, 7003]
Llama 13B	2	mlp	down_proj	[2231, 2278]
	2	mlp	down_proj	[2231, 6939]
Llama 30B	3	mlp	down_proj	[5633, 12817]
	3	mlp	down_proj	[5633, 17439]
	10	mlp	down_proj	[5633, 14386]
Llama2 7B	1	mlp	down_proj	[2533, 7890]
Llama2 13B	3	mlp	down_proj	[4743, 7678]
Mistral-7B v0.1	1	mlp	down_proj	[2070, 7310]

Model	No.	Type	Weight	Coordinates
OLMo-1B 0724-hf	1	mlp	down_proj	[1764, 1710]
	1	mlp	down_proj	[1764, 8041]
OLMo-7B 0724-hf	1	mlp	down_proj	[269, 7467]
	2	mlp	down_proj	[269, 8275]
	7	mlp	down_proj	[269, 453]
	24	mlp	down_proj	[269, 2300]
Phi-3 mini-4k-instruct	2	mlp	down_proj	[525, 808]
	2	mlp	down_proj	[1693, 808]
	2	mlp	down_proj	[1113, 808]
	4	mlp	down_proj	[525, 2723]
	4	mlp	down_proj	[1113, 2723]
	4	mlp	down_proj	[1693, 2723]

Table 2: Super Weight Directory. The above layer numbers, layer types, and weight types can be directly applied to Huggingface models. For example, for Llama-7B on Huggingface, access the super weight using `layers[2].mlp.down_proj.weight[3968, 7003]`.

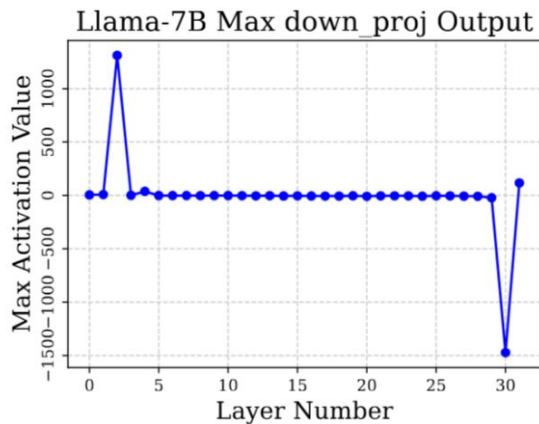
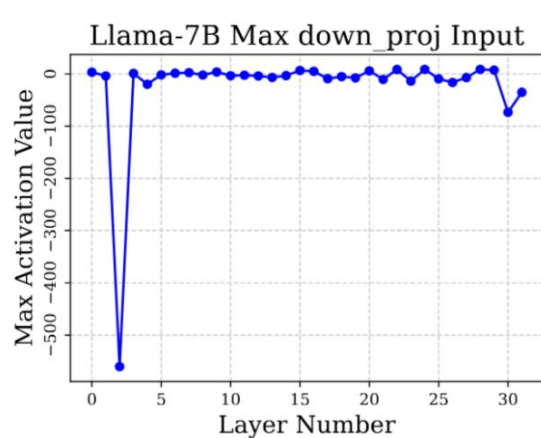


Figure 3: How to identify the Super Weight for Llama-7B. `down_proj` input features a large maximum-magnitude activation only in Layer 2, where the super activation first appeared. The value’s channel index, e.g., 7003, tells the row of SW. `down_proj` output likewise features a large maximum-magnitude activation at Layer 2. This value’s channel index, e.g., 3968, gives us the column of the SW.

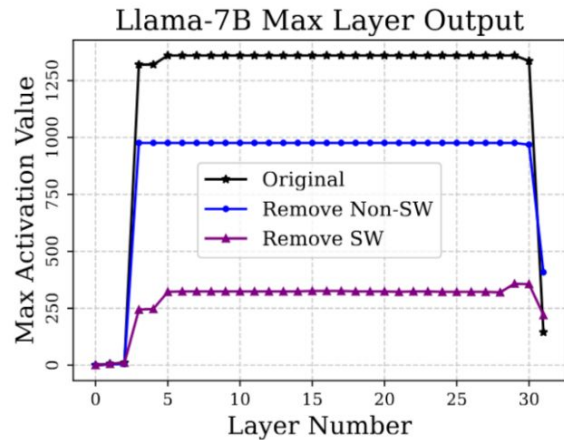


Figure 4: The super activation persists throughout the entire model, at exactly the same magnitude, starting after Layer 2. Pruning the super weight decreases the super activation’s magnitude by 75%.

Format Name	Element Data Type	Element Bits (d)	Scaling Block Size (k)	Scale Data Type	Scale Bits (w)
MXFP8	FP8 (E5M2)	8	32	E8M0	8
	FP8 (E4M3)				
MXFP6	FP6 (E3M2)	6	32	E8M0	8
	FP6 (E2M3)				
MXFP4	FP4 (E2M1)	4	32	E8M0	8
MXINT8	INT8	8	32	E8M0	8

Table 1. Format names and parameters of concrete MX-compliant formats.

GB200 Grace Blackwell Superchip		H100 NVL ¹	
Configuration	1 Grace CPU : 2 Blackwell GPU	2x H100 NVLink	Blackwell GPU
FP4 Tensor Core ²	40 PFLOPS		2.5X FP8 20 PFLOPS Hopper
FP8/FP6 Tensor Core ²	20 PFLOPS	7,916 teraFLOPs ²	NEW FP6 20 PFLOPS 2.5X NEW FP4 40 PFLOPS 5X
FP16/BF16 Tensor Core ²	10 PFLOPS	3,958 teraFLOPs ²	HBM Model Size 740B param 6X HBM Bandwidth 34T param/s 5X
GPU Memory Bandwidth Up to 384 GB HBM3e 16 TB/s		188GB	

	Exponent	Mantissa	~ Space E+M^2	x fp32
Float32	8	23	537	1
Float16	5	10	105	5
Bfloat16	8	7	57	9
Float8 E4M3	4	3	13	41
Float8 E5M2	5	2	9	60
1.58bit (E5M2)	5	2	7	77
Float4	2	1	3	179
1.58bit (Float4)	2	1	3	179

Float4 sign=1 exponent=1
mantissa=3
Wikipedia table:

	0 ... 0	0 ... 1	1 ... 0	1 ... 1
... 00 ...	0	0.5	-0	-0.5
... 01 ...	1	1.5	-1	-1.5
... 10 ...	2	3	-2	-3
... 11 ...	Inf	NaN	-Inf	NaN

Use torch.compile!

```
{'TYPE_CHECKING': False,  
 'inplace_padding': True,  
 'can_inplace_pad_graph_input': False,  
 'enable_auto_functionalized_v2': True,  
 'debug': False,  
 'disable_progress': True,  
 'verbose_progress': False,  
 'fx_graph_cache': True,  
 'fx_graph_remote_cache': None,  
 'bundle_triton_into_fx_graph_cache': True,  
 'autotune_local_cache': True,  
 'autotune_remote_cache': None,  
 'bundled_autotune_remote_cache': None,  
 'force_disable_caches': False,  
 'sleep_sec_TESTING_ONLY': None,  
 'custom_op_default_layout_constraint': 'needs_fixed_stride_order',  
 'triton_kernel_default_layout_constraint': 'needs_fixed_stride_order',  
 'cpp_wrapper': False,  
 'cpp_cache_precompile_headers': True,  
 'online_softmax': True,
```

Thank you!

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forget to
grab
stickers

